

Supersolutions in Fractional Nonlinear Problems¹

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Based on joint works with J. Korvenpää & E. Lindgren & G. Palatucci

3rd Conference on Nonlocal Operators and Partial Differential
Equations
Będlewo, June 27, 2016

¹A video of an extended version of the talk available at the Fields institute webpage (<http://www.fields.utoronto.ca/video-archive/event/2022>)

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Scope

The topic of the talk concerns nonlocal and nonlinear equations modelled by the fractional p -Laplacian in \mathbb{R}^n given by

$$(-\Delta)_p^s u(x) := \text{p.v.} \int_{\mathbb{R}^n} \frac{|u(x) - u(y)|^{p-2} (u(x) - u(y))}{|x - y|^{n+sp}} dy,$$

where $s \in (0, 1)$ and $p \in (1, \infty)$.

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where $s \in (0, 1)$ and $p \in (1, \infty)$.

- When $p = 2$, it is the fractional Laplacian (up to a normalizing constant).
- For $p \geq 2$ the, operator $(-\Delta)_p^s$ is usually called fractional p -Laplacian.
- Arises naturally from minimization of the $W^{s,p}$ -seminorm. Some aspects of the talk are relevant already in the case $p = 2$.

Scope

Our goal is to understand Dirichlet boundary value problems in a bounded open set Ω of the type

$$\begin{cases} (-\Delta)_p^s u = 0 & \text{in } \Omega \subseteq \mathbb{R}^n \\ u = g & \text{a.e. on } \mathbb{R}^n \setminus \Omega, \end{cases}$$

where boundary values g can be “rough” and the domain Ω “irregular”.

Scope: Perron method

For given boundary datum g , the goal is to find some classes of functions, say \mathcal{U}_g (or \mathcal{L}_g), with correct boundary values, and which are lower (or upper) directed. This means that if $u, v \in \mathcal{U}_g$ (or \mathcal{L}_g), then $\min(u, v) \in \mathcal{U}_g$ (or $\max(u, v) \in \mathcal{L}_g$).

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$$\overline{H}_g(x) := \inf_{u \in \mathcal{U}_g} u(x) \quad \left(\text{or } \underline{H}_g(x) := \sup_{u \in \mathcal{L}_g} u(x) \right)$$

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- Solvability: Both \overline{H}_g and \underline{H}_g are solutions in Ω
- Resolutivity: $\overline{H}_g = \underline{H}_g$
- Wiener criterion: Give a necessary and sufficient condition for the geometry of the boundary at a point $z \in \partial\Omega$ such that if g is “continuous at z ”, then so are \overline{H}_g and \underline{H}_g .

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Question: Can one do this in the case of the operator $(-\Delta)_p^s$?

Different notions of supersolutions

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1. *Weak supersolutions.* Satisfy the weak formulation against smooth test functions together with fractional integrability.
2. *(s, p) -superharmonic functions.* These are defined via comparison against weak solutions.
3. *(s, p) -viscosity supersolutions.* The notion of viscosity solutions is based on the pointwise evaluation of the principal value appearing in the definition of $(-\Delta)_p^s$:

$$(-\Delta)_p^s u(x) := \text{p.v.} \int_{\mathbb{R}^n} \frac{|u(x) - u(y)|^{p-2} (u(x) - u(y))}{|x - y|^{n+sp}} dy.$$

Fractional Sobolev space

We first define the natural energy spaces for the problem. The fractional Sobolev space $W^{s,p}$ is defined via Gagliardo-seminorm

$$[u]_{W^{s,p}(\Omega)} := \left(\int_{\Omega} \int_{\Omega} \frac{|u(x) - u(y)|^p}{|x - y|^{n+sp}} dx dy \right)^{1/p}$$

as

$$W^{s,p}(\Omega) := \{u \in L^p(\Omega) : [u]_{W^{s,p}(\Omega)} < \infty\}$$

The local version $W_{\text{loc}}^{s,p}(\Omega)$ is defined in an obvious way.

Tail space

The second space controls the behavior of tails:

$$L_{sp}^{p-1}(\mathbb{R}^n) := \left\{ u \in L_{\text{loc}}^{p-1}(\mathbb{R}^n) : \int_{\mathbb{R}^n} \frac{|u(x)|^{p-1}}{(1+|x|)^{n+sp}} dx < \infty \right\}.$$

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In particular, $u \in L_{sp}^{p-1}(\mathbb{R}^n)$ implies that in the definition of $(-\Delta)_s^p u$ the nonlocal contributions are finite:

If $|u(x)| < \infty$ and $u \in L_{sp}^{p-1}(\mathbb{R}^n)$, then

$$\left| \int_{\mathbb{R}^n \setminus B_r(x)} \frac{|u(x) - u(y)|^{p-2} (u(x) - u(y))}{|x - y|^{n+sp}} dy \right| < \infty$$

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Moreover, a very natural quantity

$$\text{Tail}(u; z, r) := \left(r^{sp} \int_{\mathbb{R}^n \setminus B_r(z)} \frac{|u(x)|^{p-1}}{|x - z|^{n+sp}} dx \right)^{\frac{1}{p-1}}$$

appearing in the theory frequently is finite for all $z \in \mathbb{R}^n$ and $r > 0$ provided that $u \in L_{sp}^{p-1}(\mathbb{R}^n)$.

Weak solutions: Definition

Let us begin with the definition

Definition

We say that u is a weak supersolution to $(-\Delta)_p^s u = 0$ in Ω if $u \in W_{\text{loc}}^{s,p}(\Omega) \cap L_{sp}^{p-1}(\mathbb{R}^n)$ satisfies

$$\begin{aligned} & \langle (-\Delta)_p^s u, \phi \rangle \\ & := \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \frac{|u(x) - u(y)|^{p-2} (u(x) - u(y)) (\phi(x) - \phi(y))}{|x - y|^{n+sp}} dx dy \geq 0 \end{aligned}$$

whenever ϕ belongs to $C_0^\infty(\Omega)$ and is nonnegative. Similarly, u is a weak subsolution if $-u$ is a weak supersolution, and u is a weak solution if it is both sub- and supersolution.

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The definition still makes sense with measurable coefficients, i.e., if the kernel $|x - y|^{-n-sp}$ is replaced with $K(x, y) = a(x, y)|x - y|^{-n-sp}$, where a is symmetric, measurable and satisfies for example $\Lambda^{-1} \leq a(x, y) \leq \Lambda$ for a.e. x, y with a constant $\Lambda \geq 1$.

Initial motivation for the problem: Minimization

Weak solutions naturally appear in minimization problems. Defining, for $g \in W^{s,p}(\mathbb{R}^n)$,

$$\mathcal{K}_g(\Omega) := \{u \in W^{s,p}(\mathbb{R}^n) : u = g \text{ a.e. on } \mathbb{R}^n \setminus \Omega\},$$

then the minimizer of

$$\min_{u \in \mathcal{K}_g(\Omega)} [u]_{W^{s,p}(\mathbb{R}^n)}$$

is a weak solution in Ω , with boundary values g , by the first variation.

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There are various ways to generalize this. For instance, letting Ω' be such that $\Omega \Subset \Omega'$ and defining, for $g \in W^{s,p}(\Omega') \cap L_{sp}^{p-1}(\mathbb{R}^n)$,

$$\mathcal{K}_g(\Omega, \Omega') := \{u \in W^{s,p}(\Omega') \cap L_{sp}^{p-1}(\mathbb{R}^n) : u = g \text{ a.e. on } \mathbb{R}^n \setminus \Omega\},$$

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Problem: What can be said if g does not belong to $W^{s,p}(\Omega')$ for any $\Omega' \ni \Omega$?

Weak solutions: Some properties

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- Many other recent results
- Higher regularity still open

Weak supersolutions

Weak supersolutions play an important role in the theory.

Some basic properties of supersolutions are the following (Korvenpää-K-Palatucci, preprint):

- A weak supersolution has a lower semicontinuous (l. s. c.) representative
- Class of uniformly globally bounded weak supersolutions is closed w.r.t. pointwise convergence
- Minimum of two weak supersolutions is a weak supersolution as well
- A nonnegative supersolution u in $B_R(z)$ satisfies

$$\left(\int_{B_r} u^q(x) dx \right)^{1/q} \lesssim \operatorname{ess\,inf}_{B_r} u + \left(\frac{r}{R} \right)^{\frac{sp}{p-1}} \operatorname{Tail}(\max(-u, 0); z, R)$$

whenever $r \in (0, R/2)$. Here $q \in \left(0, \frac{n(p-1)}{n-ps}\right)$ for $n > ps$ and $q \in (0, \infty)$ for $n \leq ps$.

$$\text{Recall: } \operatorname{Tail}(f; z, r) := \left(r^{sp} \int_{\mathbb{R}^n \setminus B_r(z)} \frac{|f(x)|^{p-1}}{|x-z|^{n+sp}} dx \right)^{\frac{1}{p-1}}$$

(s, p) -superharmonic functions

Definition

We say that a function $u : \mathbb{R}^n \rightarrow [-\infty, \infty]$ is an (s, p) -superharmonic function in an open set Ω if it satisfies the following four assumptions:

- (i) $u < +\infty$ almost everywhere and $u > -\infty$ everywhere in Ω ,
- (ii) u is lower semicontinuous (l. s. c.) in Ω ,
- (iii) u satisfies the comparison in Ω against solutions bounded from above; that is, if $D \Subset \Omega$ is an open set and $v \in C(\overline{D})$ is a weak solution in D such that $\max\{v, 0\} \in L^\infty(\mathbb{R}^n)$ and $u \geq v$ on ∂D and almost everywhere on $\mathbb{R}^n \setminus D$, then $u \geq v$ in D ,
- (iv) u_- belongs to $L_{sp}^{p-1}(\mathbb{R}^n)$.

A function u is (s, p) -subharmonic in Ω if $-u$ is (s, p) -superharmonic in Ω , and if both u and $-u$ are (s, p) -superharmonic, we say that u is (s, p) -harmonic.

Properties of (s, p) -superharmonic functions

Theorem (Korvenpää-K-Palatucci, preprint)

Suppose that u is (s, p) -superharmonic in an open set Ω . Then it has the following properties:

(i) **Pointwise behavior.**

$$u(x) = \liminf_{y \rightarrow x} u(y) = \operatorname{ess\,lim\,inf}_{y \rightarrow x} u(y) \quad \text{for every } x \in \Omega.$$

(ii) **Summability.** For

$$\bar{t} := \begin{cases} \frac{(p-1)n}{n-sp}, & 1 < p < \frac{n}{s}, \\ +\infty, & p \geq \frac{n}{s}, \end{cases} \quad \bar{q} := \min \left\{ \frac{n(p-1)}{n-s}, p \right\},$$

and $h \in (0, s)$, $t \in (0, \bar{t})$ and $q \in (0, \bar{q})$,

$$u \in W_{\operatorname{loc}}^{h,q}(\Omega) \cap L_{\operatorname{loc}}^t(\Omega) \cap L_{sp}^{p-1}(\mathbb{R}^n).$$

(iii) **Connection to weak supersolutions.** If u is locally bounded in Ω or $u \in W_{\operatorname{loc}}^{s,p}(\Omega)$, then it is a weak supersolution in Ω .

Perron solutions

We may now define the upper (and lower) classes for the Perron solution

Definition (Perron solutions)

Let Ω be an open set. Assume that $g \in L_{sp}^{p-1}(\mathbb{R}^n)$. The upper class \mathcal{U}_g of g consists of all functions u such that

- (i) u is (s, p) -superharmonic in Ω ,
- (ii) u is bounded from below in Ω ,
- (iii) $\liminf_{\Omega \ni y \rightarrow x} u(y) \geq \operatorname{ess\,lim\,sup}_{\mathbb{R}^n \setminus \Omega \ni y \rightarrow x} g(y)$ for all $x \in \partial\Omega$,
- (iv) $u = g$ almost everywhere in $\mathbb{R}^n \setminus \Omega$.

The lower class is $\mathcal{L}_g := \{u : -u \in \mathcal{U}_{-g}\}$. Define

$$\overline{H}_g := \inf \{u : u \in \mathcal{U}_g\} \quad \text{and} \quad \underline{H}_g := \sup \{u : u \in \mathcal{L}_g\}.$$

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The definition (and some work) guarantees that $\bar{H}_g \geq \underline{H}_g$.

Theorem (Korvenpää-K-Palatucci, preprint)

The Perron solution \bar{H}_g (\underline{H}_g) can be either identically $+\infty$ in Ω , identically $-\infty$ in Ω , or (s, p) -harmonic in Ω .

A few examples

The function

$$u(x) = c_{n,s} (1 - |x|^2)^s \int_{\mathbb{R}^n \setminus B_1(0)} g(y) (|y|^2 - 1)^{-s} |x - y|^{-n} dy, \quad x \in B_1(0),$$

solves $(-\Delta)^s u = 0$ in $B_1(0)$ with $u = g$ on $\mathbb{R}^n \setminus B_1(0)$.

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Example

Taking the function $g(x) = ||x|^2 - 1|^{s-1}$, $g \in L^1_{2s}(\mathbb{R}^n)$, as boundary values in the Poisson formula above, the integral does not converge. This example suggests that in this case $\overline{H}_g \equiv \underline{H}_g \equiv +\infty$ in $B_1(0)$. The example also tells that one can not expect bounded solutions for all $g \in L^1_{2s}(\mathbb{R}^n)$.

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Example

Let us consider the previous example with g reflected to the negative side in the half space, i. e., $g(x) = \text{sign}(x_n) ||x|^2 - 1|^{s-1}$. Then the “solution” via Poisson formula, for $x \in B_1$, is $u(x) = \text{sign}(x_n) \cdot \infty$. which is suggesting that we should now have $\overline{H}_g \equiv +\infty$ and $\underline{H}_g \equiv -\infty$ in $B_1(0)$: failure of resolutive in $L^1_{2s}(\mathbb{R}^n)$?

“Viscosity” solutions

Let us finally comment another possible class for upper solutions, namely viscosity supersolutions.

Definition

We say that a function $u : \mathbb{R}^n \rightarrow [-\infty, \infty]$ is an (s, p) -viscosity supersolution in Ω if it satisfies the following four assumptions.

- (i) $u < +\infty$ almost everywhere in \mathbb{R}^n , and $u > -\infty$ everywhere in Ω .
- (ii) u is lower semicontinuous in Ω .
- (iii) If $\phi \in C^2(B_r(x_0))^3$ for some $B_r(x_0) \subseteq \Omega$ is such that $\phi(x_0) = u(x_0)$ and $\phi \leq u$ in $B_r(x_0)$, then $(-\Delta)_p^s \phi_r(x_0) \geq 0$, where

$$\phi_r(x) = \begin{cases} \phi(x), & x \in B_r(x_0), \\ u(x), & x \in \mathbb{R}^n \setminus B_r(x_0). \end{cases}$$

- (iv) u_- belongs to $L_{sp}^{p-1}(\mathbb{R}^n)$.

³Replacing C^2 with Dini- $C^{\frac{sp}{p-1}}$ for $p > \frac{2}{2-s}$ leads to the same class. The case $1 < p \leq \frac{2}{2-s}$ needs an extra assumption on the critical set of ϕ .

Equivalence

It turns out that the classes of (s, p) -superharmonic functions and (s, p) -viscosity solutions are the same.

Theorem (Korvenpää-K-Lindgren)

A function u is (s, p) -superharmonic in Ω if and only if it is an (s, p) -viscosity supersolution in Ω .

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It turns out that the classes of (s, p) -superharmonic functions and (s, p) -viscosity solutions are the same.

Theorem (Korvenpää-K-Lindgren)

A function u is (s, p) -superharmonic in Ω if and only if it is an (s, p) -viscosity supersolution in Ω .

As an immediate corollary we get:

Theorem (Korvenpää-K-Lindgren)

A function u is a continuous weak solution to $(-\Delta)_p^s u = 0$ in Ω if and only if it is an (s, p) -viscosity solution in Ω .

The proof

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- Let ϕ be s.t. $u \geq \phi$ in $B_r(z)$ and $u(z) = \phi(z)$. Assume on contrary that $(-\Delta)_p^s \phi_r(z) < 0$.

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- $(-\Delta)_p^s(\phi_r + \delta\eta)(\cdot) < 0$ for small enough $\delta > 0$ and η a cut-off function in the neighborhood of z by the counter assumption (**this is where the most of the computations happen**)

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- Show that

$$\left| \int_{B_r(x) \setminus B_\varepsilon(x)} \frac{|\phi(x) - \phi(y)|^{p-2} (\phi(x) - \phi(y))}{|x - y|^{n+sp}} dy \right| = O(r)$$

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- “Integrate by parts” to show that $\phi_r + \delta\eta$ is a weak subsolution
- Use the comparison principle for weak super- and subsolutions to reach a contradiction

The proof

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- Take a domain $D \Subset \Omega$ and a continuous weak solution v s.t. $u \geq v$ on ∂D and a.e. on $\mathbb{R}^n \setminus D$.

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- As in the first part, one can show that v is an (s, p) -viscosity subsolution
- Conclude the proof by proving a comparison principle for viscosity solutions (**MUCH easier than in the case of local viscosity solutions**)

Thank you for your attention!