

# Computation of conditional expectations in jump-diffusion setting

Applied to pricing and hedging of financial products

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# Option pricing and hedging

$S$ : stock price process

$T$ : time of maturity

$r$ : risk-free interest rate

$\Phi$ : payoff function

- European option

$$P^{Eu}(t, S_t) = e^{-r(T-t)} \mathbb{E}[\Phi(S_T) | S_t],$$

$$\Delta^{Eu}(t, S_t) = \frac{\partial}{\partial S_t} P^{Eu}(t, S_t),$$

- American option pricing and hedging

Conditional expectations  $\mathbb{E}[f(S_t)|S_s = \alpha]$ ,  $\alpha \in \mathbb{R}^+$ ,  $s < t$

- Bayes rule

$$\mathbb{E}[f(S_t)|S_s = \alpha] = \frac{\mathbb{E}[f(S_t)\delta_0(S_s - \alpha)]}{\mathbb{E}[\delta_0(S_s - \alpha)]}$$

- For **continuous** stock price processes  $S$ :

$$\mathbb{E}[f(S_t)|S_s = \alpha] = \frac{\mathbb{E}[f(S_t)H(S_s - \alpha)\pi]}{\mathbb{E}[H(S_s - \alpha)\pi]},$$

$$H(x) = \mathbf{1}_{\{x>0\}} + c, c \in \mathbb{R}$$

See Fournié et al. (1999) ,Fournié et al. (2001).

## Methods

- For **discontinuous** stock price processes:

$$\mathbb{E}[f(S_t)|S_s = \alpha] = \frac{\mathbb{E}[f(S_t)H(S_s - \alpha)\pi]}{\mathbb{E}[H(S_s - \alpha)\pi]}, \quad s < t,$$

$H(x) = \mathbf{1}_{\{x>0\}} + c$ , based on two methods:

- Conditional density method
- Malliavin approach

# Outline

## I- Conditional density method

1. Representations
2. Optimal weights
3. Delta

## II- Malliavin calculus

1. Representations
2. Delta

## III- Numerical methods and results

1. American options
2. Monte Carlo simulation
3. Numerical example

# Outline

## I- Conditional density method

# 1. Representations

Conditional density method for  $\mathbb{E}[f(F)|G = \alpha]$

$F$  and  $G$  are two random variables such that

$$F = g_1(X, Y) \quad \text{and} \quad G = g_2(U, V),$$

- $(X, U)$  independent of  $(Y, V)$
- $X$  and  $U$  allowed to be dependent, joint density  $p_{(X,U)}$

Under the necessary assumptions

$$\mathbb{E}[f(F)|G = \alpha] = \frac{\mathbb{E}[f(F)H(G - \alpha)\pi_{(X,U)}]}{\mathbb{E}[H(G - \alpha)\pi_{(X,U)}]},$$

where  $H = \mathbf{1}_{\{x>0\}} + c$  and

$$\pi_{(X,U)} = -\frac{\partial}{\partial u} \log p_{(X,U)}(X, U).$$

See Benth et al. (2010).

## CDM applied to an exponential Lévy process

Observe  $S = S_0 e^L$ , where  $L$  is a Lévy process with decomposition

$$L_t = at + bW_t + \tilde{N}_t, \quad t \in [0, T]$$

$W$  is a standard Brownian motion,

$\tilde{N}$  is a compound Poisson process, independent of  $W$

$$(X, U) = (bW_t, bW_s)$$

For any Borel measurable function  $f$  and positive number  $\alpha$ ,

$$\mathbb{E}[f(S_t) | S_s = \alpha] = \frac{\mathbb{E}[f(S_t) H(S_s - \alpha) \pi]}{\mathbb{E}[H(S_s - \alpha) \pi]},$$

where

$$\pi = \frac{tW_s - sW_t}{bs(t - s)}$$



## Examples of stock price processes

$$\mathbb{E}[f(S_t)|S_s = \alpha], \quad s < t$$

- Geometric Brownian motion → regular density method
- Additive model  $S = A + B$ , where  $A$  is an Ornstein-Uhlenbeck process
- Approximation of jump process by replacing the small jumps by a scaled Brownian motion, e.g. NIG process

See Asmussen and Rosinski (2001).

## 2. Optimal weights

- For any  $\pi$  in  $\mathcal{W} := \{\pi : \mathbb{E}[\pi | \sigma(F, G)] = \pi_{(X, U)}\}$   
it is clear

$$\mathbb{E}[f(F)H(G - \alpha)\pi] = \mathbb{E}[f(F)H(G - \alpha)\pi_{(X, U)}]$$

- In this set  $\mathcal{W}$ , the variance

$$\text{Var}(f(F)H(G - \alpha)\pi) = \mathbb{E}[(f(F)H(G - \alpha)\pi)^2] - \mathbb{E}[f(F)H(G - \alpha)\pi]^2$$

is **minimized** for  $\pi = \pi_{(X, U)}$

- Different weight denominator

$$\mathbb{E}[\delta_0(G - \alpha)] = \mathbb{E}[H(G - \alpha)\pi_{(X, U)}] = \mathbb{E}[H(G - \alpha)\pi_U],$$

$$\text{where } \pi_U = -\frac{\partial}{\partial u} \log p_U(U)$$

### 3.Delta

$$\mathbb{E}[f(F)|G = \alpha] = \frac{\mathbb{E}[f(F)H(G - \alpha)\pi_{(X,U)}]}{\mathbb{E}[H(G - \alpha)\pi_{(X,U)}]} =: \frac{\mathbb{A}_{F,G}[f](\alpha)}{\mathbb{A}_{F,G}[1](\alpha)}$$

$$\frac{\partial}{\partial \alpha} \mathbb{E}[f(F)|G = \alpha] = \frac{\mathbb{B}_{F,G}[f](\alpha)\mathbb{A}_{F,G}[1](\alpha) - \mathbb{A}_{F,G}[f](\alpha)\mathbb{B}_{F,G}[1](\alpha)}{\mathbb{A}_{F,G}[1](\alpha)^2}$$

where  $\mathbb{A}_{F,G}[\cdot](\alpha) = \mathbb{E}[\cdot(F)H(G - \alpha)\pi_{(X,U)}]$

$$\begin{aligned} \mathbb{B}_{F,G}[\cdot](\alpha) &= \frac{\partial}{\partial \alpha} \mathbb{A}_{F,G}[\cdot](\alpha) \\ &= \mathbb{E}[\cdot(F)H(G - \alpha)\{\pi_{(X,U)}^* - \pi_{(X,U)}^2\}]h'(\alpha) \end{aligned}$$

$$\pi_{(X,U)} = -\frac{\partial}{\partial u} \log p_{(X,U)}(X, U)$$

$$\pi_{(X,U)}^* = -\frac{\partial^2}{\partial u^2} \log p_{(X,U)}(X, U)$$

# Outline

## II- Malliavin approach

# 1. Malliavin calculus

- Standard Brownian motion  $W$ , pure jump process  $J$ , then Lévy process  $L = \Gamma(W, J)$
- **The Malliavin derivative**  $D_{r,0}$ ,  $r \in [0, T]$  of a Lévy process is essentially a derivative with respect to the Brownian part

$$\text{e.g. } D_{r,0}(W_t + J_t) = \mathbf{1}_{r \leq t}$$

- **Skorohod integral** of an adapted process  $u$ :

$$\delta(u) = \int_0^T u_r dW_r$$

- Chain rule, Integration by parts, Duality formula

See Nualart (1995) and solé et al. (2007).

## 2. Representations

### First representation

$F$  and  $G$  two random variables such that

$$F = g_1(X^c, X^d) \quad \text{and} \quad G = g_2(U^c, U^d) \quad (1)$$

#### Theorem

Assume  $f$  differentiable and  $F$  and  $G$  as described in (1).

For a Skorohod integrable process  $u$  satisfying

$$\mathbb{E} \left[ \int_0^T D_{t,0} G u_t dt \mid \sigma(F, G) \right] = 1,$$

it holds

$$\mathbb{E}[f(F) \mid G = \alpha] = \frac{\mathbb{E} \left[ f(F) H(G - \alpha) \delta(u) - f'(F) H(G - \alpha) \int_0^T D_{t,0} F u_t dt \right]}{\mathbb{E} [H(G - \alpha) \delta(u)]}$$

## Representation 2

### Theorem

Assume again the setting of Theorem 1 and in addition that  $u$  is a Skorohod integrable process, satisfying

$$\mathbb{E} \left[ \int_0^T D_{t,0} F u_t dt \mid \sigma(F, G) \right] = 0.$$

Then we have the following representation

$$\mathbb{E}[f(F) \mid G = \alpha] = \frac{\mathbb{E}[f(F) H(G - \alpha) \delta(u)]}{\mathbb{E}[H(G - \alpha) \delta(u)]}$$

# Malliavin method applied to linear SDE

Stock price process modeled by the linear SDE

$$\begin{cases} dS_t &= \alpha S_t dt + \beta S_t dW_t + \int_{\mathbb{R}_0} (e^z - 1) S_t \tilde{N}(dt, dz), \\ S_0 &= x \end{cases}$$

In Benth et al. (2001), it is shown  $S_t = S_t^c e^{S_t^d}$

$$\mathbb{E}[f(S_t) | S_s = \alpha] = \frac{\mathbb{E}\left[f(S_t) H(S_s - \alpha) \frac{1}{S_s} \left(\frac{W_s}{s\beta} + 1\right) - f'(S_t) H(S_s - \alpha) \frac{S_t}{S_s}\right]}{\mathbb{E}\left[H(S_s - \alpha) \frac{1}{S_s} \left(\frac{W_s}{s\beta} + 1\right)\right]}$$

$$\mathbb{E}[f(S_t) | S_s = \alpha] = \frac{\mathbb{E}\left[f(S_t) H(S_s - \alpha) \frac{1}{S_s} \left(\frac{tW_s - sW_t}{s(t-s)\beta} + 1\right)\right]}{\mathbb{E}\left[H(S_s - \alpha) \frac{1}{S_s} \left(\frac{tW_s - sW_t}{s(t-s)\beta} + 1\right)\right]}$$



## Examples of stock price processes

- Geometric Brownian motion, see Bally et al. (2005)
- Jump-diffusion model
- Stochastic differential equations, in particular:
  - Linear SDE
  - Stochastic volatility model

### 3. Delta

#### Theorem

Consider the same setting as in [Theorem 2](#) and that the Skorohod integral  $\delta(u)$  is  $\sigma(F, G)$ -measurable. Then

$$\frac{\partial}{\partial \alpha} \mathbb{E}[f(F)|G = \alpha] = \frac{\mathbb{B}_{F,G}[f](\alpha)\mathbb{A}_{F,G}[1](\alpha) - \mathbb{A}_{F,G}[f](\alpha)\mathbb{B}_{F,G}[1](\alpha)}{\mathbb{A}_{F,G}^2[1](\alpha)},$$

where

$$\mathbb{A}_{F,G}[\cdot](\alpha) = \mathbb{E}[\cdot(F)H(G - \alpha)\delta(u)],$$

$$\mathbb{B}_{F,G}[\cdot](\alpha) = \mathbb{E}\left[\cdot(F)H(G - \alpha)\left\{-\delta^2(u) + \int_0^T u_r D_{r,0}\delta(u)dr\right\}\right]$$

# Outline

III- Numerical methods and results

# 1. American options

## Pricing algorithm for American options

- Payoff function  $\Phi$ , stock price process  $S$  with initial value  $x$
- Approximated by Bermudan option, discretization of time interval into  $n$  periods with step size  $\varepsilon = \frac{T}{n}$
- Priced iteratively via the Bellman dynamic programming principle:

$$P_{n\varepsilon}(S_{n\varepsilon}) \equiv \Phi(S_{n\varepsilon}) = \Phi(S_T),$$

$$P_{k\varepsilon}(S_{k\varepsilon}) = \max \left\{ \Phi(S_{k\varepsilon}), e^{-r\varepsilon} \mathbb{E} \left[ P_{(k+1)\varepsilon}(S_{(k+1)\varepsilon}) \mid S_{k\varepsilon} \right] \right\},$$

$$k = n - 1, \dots, 1, 0$$

- Delta of the option  $\Delta_0(x) := \partial_x P_0(x)$ ,

$$\Delta_\varepsilon(S_\varepsilon) = \begin{cases} \partial_\alpha \Phi(\alpha) \Big|_{\alpha=S_\varepsilon} & \text{if } P_\varepsilon(\alpha) < \Phi(\alpha), \\ e^{-r\varepsilon} \partial_\alpha \mathbb{E} \left[ P_{2\varepsilon}(S_{2\varepsilon}) \mid S_\varepsilon = \alpha \right] \Big|_{\alpha=S_\varepsilon} & \text{if } P_\varepsilon(\alpha) \geq \Phi(\alpha), \end{cases}$$

$$\Delta_0(x) = \mathbb{E}_x[\Delta_\varepsilon(S_\varepsilon)]$$

## 2. Monte Carlo estimation

- For the conditional expectations we make use of the representation

$$\mathbb{E}\left[P_{(k+1)\varepsilon}(S_{(k+1)\varepsilon}) \mid S_{k\varepsilon} = S_{k\varepsilon}^q\right] = \frac{\mathbb{E}\left[P_{(k+1)\varepsilon}(S_{(k+1)\varepsilon})H(S_{k\varepsilon} - S_{k\varepsilon}^q)\pi_k\right]}{\mathbb{E}\left[H(S_{k\varepsilon} - S_{k\varepsilon}^q)\pi_k\right]}$$

and the Monte Carlo estimation

$$\mathbb{E}\left[.(S_{(k+1)\varepsilon})H(S_{k\varepsilon} - \alpha)\pi_k\right] \approx \frac{1}{N} \sum_{j=1}^N .(S_{(k+1)\varepsilon}^j)H(S_{k\varepsilon}^j - \alpha)\pi_k^j$$

- Pricing algorithm: backward in time

⇒ backward simulation of the stock price process,  
to obtain a better efficiency

Possible for GBM model Bally et al. (2005), Merton model.

### 3. Variance reduction

- Localization technique
- Including a control variable

### 3. Numerical example

- American put option on a stock price given by the Merton model

$$S_t = S_0 \exp \left( (r - \sigma^2/2)t + \sigma W_t + \sum_{i=1}^{N_t} Z_i \right)$$

$W$ : standard Brownian motion

$N$ : Poisson process with intensity  $\mu$

$Z_i$ : i.i.d.  $N(-\delta^2/2, \delta^2)$

- Weight in the representation

$$\pi_{\text{CDM}} = \frac{tW_s - sW_t}{\sigma s(t-s)} \quad \text{and} \quad \pi_{\text{MM}} = \frac{1}{S_s} \left( \frac{tW_s - sW_t}{\sigma s(t-s)} + 1 \right)$$

- Parameter set, see Amin (1993)

$T$	$S_0$	$r$	$\sigma^2$	$\mu$	$\delta^2$
0.25	40	0.08	0.05	5	0.05

## Numerical example

Results for  $n = 10$  time periods and  $N = 10000$  simulated paths

strike	Eur Opt	CDM	CDM+L	MM	MM+L	Amin
30	0.681	2.077	1.412	0.520	0.807	0.674
<b>35</b>	<b>1.686</b>	<b>4.579</b>	<b>2.602</b>	<b>1.409</b>	<b>1.830</b>	<b>1.688</b>
40	3.605	7.903	4.562	3.403	3.772	3.630
45	6.660	11.761	7.687	6.491	6.837	6.734
50	10.548	16.502	11.744	10.569	10.772	10.696

Increasing the number of simulated paths to  $N = 30000$

strike	Eur Opt	CDM	CDM+L	MM	MM+L	Amin
35	1.693	1.5120	1.8998	2.120	1.757	1.688



## Conclusion

For **discontinuous** stock price processes:

$$\mathbb{E}[f(S_t)|S_s = \alpha] = \frac{\mathbb{E}[f(S_t)H(S_s - \alpha)\pi]}{\mathbb{E}[H(S_s - \alpha)\pi]}, \quad s < t,$$

based on two methods

- Conditional density method
- Malliavin approach
  
- **Work in progress**
  - Multidimensional setting
  - Path-dependent payoff (Asian options)
  - Backward simulation of Lévy processes

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