

Scenario Aggregation for Solvency Regulation

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Outline

Risk-Based Solvency Regulation

Is Risk-Based Market Consistency Too Expensive?

Scenario Aggregation in the Swiss Solvency Test

Minimum ϕ -Divergence Approach

- Minimum ϕ -Divergence Scenario Aggregation

- Robustness of Capital Requirement

- Solving the Optimization Problem

- Example: Relative Entropy

Case Studies

- Case Study 1

- Case Study 2

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Insurance Solvency in 1990s

- ▶ Deregulation of insurance markets
- ▶ Growth and competition based on unrealistic guarantees
- ▶ Solvency regulation with focus on liabilities
- ▶ No asset risk assessment
- ▶ Dot-com bubble: insurers buy equities . . .
- ▶ Insolvencies world-wide (Nissan Mutual Life, Equitable Life, HIH Insurance Group, . . .)

Insurance Solvency in 2000s

2001: Solvency II project initiated

2003: Swiss Solvency Test (SST) initiated

- ▶ Quantitative impacts studies (Solvency II and SST)

2008: SST mandatory for large insurers

2011: SST in force

- ▶ ...

2016: Enforcement of Solvency II

SST: Some Key Principles

- ▶ Risk based: market, insurance, and credit risks are quantified
- ▶ Market consistent valuation of assets and liabilities
- ▶ Total balance sheet approach
- ▶ **Stress scenarios**: to be aggregated for capital requirement
- ▶ **Internal models** encouraged: to be approved by regulator

SST: Available and Required Capital

- ▶ Available capital $C = \text{Assets} - \text{Liabilities}$
- ▶ Annual loss $L = C(0) - C(1)$
- ▶ Required capital $K = \text{ES}[L]$ (expected shortfall)
- ▶ Capital requirement: $C > K$

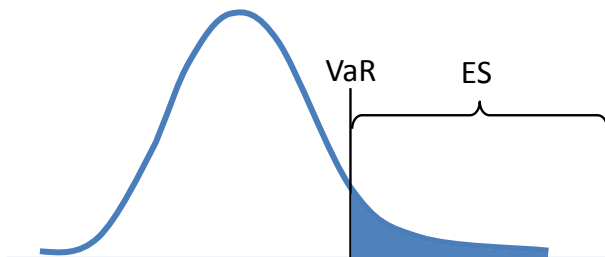


Figure: VaR = 99%-Value at Risk, ES = 99%-Expected Shortfall

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SST Results 2011–2012

► Significant difference between business models

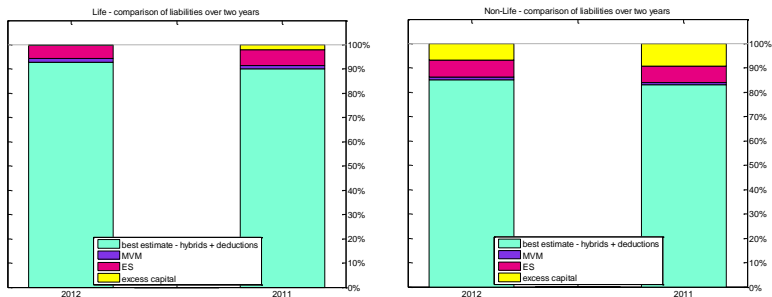
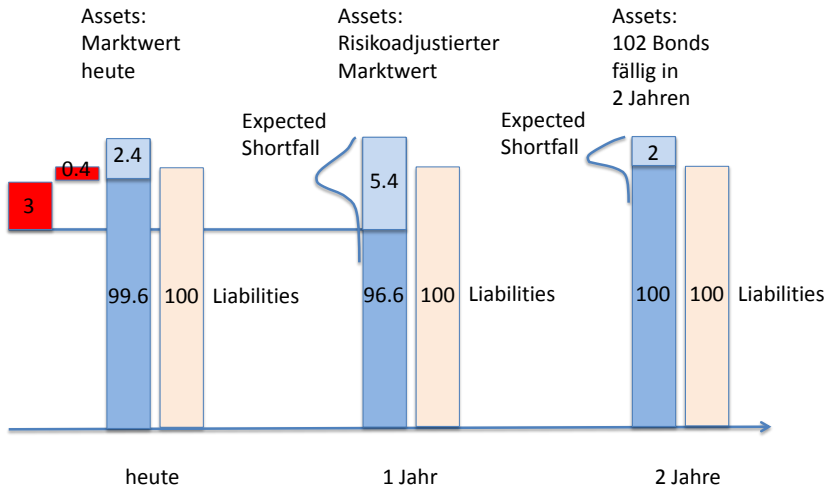


Figure: Life and non-life results. Source: FINMA SST Survey 2012

Example

- ▶ Liabilities: 100 due in 2 years
- ▶ Risk-free discount rate is zero
- ▶ Assets: 102 corporate bonds (BBB) well diversified
- ▶ Maturity of bonds in 2 years
- ▶ Default probability: 0.5%
- ▶ Recovery rate: 40%
- ▶ Spread today: 2%
- ▶ Absolute spread volatility: 1.4%

Example: Figure



Example: Result

- ▶ Expected one-in-one hundred year loss (expected shortfall) at maturity in 2 years is fully absorbed
- ▶ Even so there results an additional capital requirement of 3.4
- ▶ Explanation: market consistency means
 1. Positive spot market value at any time (liquidation vs. going-concern view)
 2. Spread risk is fully charged (“fictitious risk”?)
- ▶ Are these costs justified, or is SST economically inefficient?

Example: Relevance

- Spread risk accounts up to 30–50% of total risk

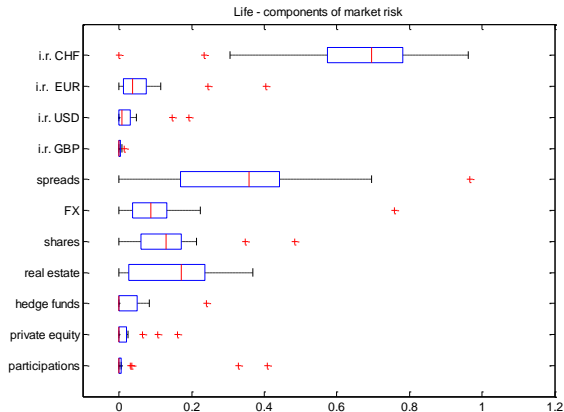


Figure: Components of market risk. Source: FINMA SST Survey 2012

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Internal Models

- ▶ Probability space $(\Omega, \mathcal{F}, \mathbb{P})$
- ▶ Annual loss L : random variable assigning a loss $L(\omega)$ to any possible state of the world $\omega \in \Omega$

$\hookrightarrow (\Omega, \mathcal{F})$ is universal

$\hookrightarrow \mathbb{P}$ and L is insurer specific (internal model)

Assumption:

Regulator trusts the mapping $L : \Omega \rightarrow \mathbb{R}$ (no ambiguity)

Fact:

Regulator wants to challenge \mathbb{P} , or distribution $F_L(x) = \mathbb{P}[L \leq x]$

Scenarios

A scenario is an event $S \in \mathcal{F}$: *a narrative description of a possible state of the world*

For factor models, this notion includes

- ▶ **point scenarios** $S = \{\mathbf{x} \in \mathbb{R}^n \mid x_j = c_j \text{ for some } j\}$, e.g.
 - ↪ 1-year loss of EUR 100 mio in Eurowind,
 - ↪ 1-year drop of -20% for SMI,
- ▶ **quadrants** $S = \{\mathbf{x} \in \mathbb{R}^n \mid x_j \geq c_j \text{ for some } j\}$, e.g.
 - ↪ 1-year change in EURCHF $\leq -20\%$,
 - ↪ 1-year change European Credit Spreads AAA $\geq 50\%$.

Scenarios from a Regulatory point of view

“Mit den SST-Szenarien sollen die Mängel aus verteilungsbasierten Modellen korrigiert werden. So können analytische Modelle extreme Ereignisse oft nur unzureichend abbilden, sowohl in Bezug auf die Heavy-Tailedness der Randverteilungen als auch in Bezug auf die so genannte Tail-Dependency.”

— FINMA, *Wegleitung für die Erarbeitung des SST-Berichtes 2013*, 2012

SST Scenario Aggregation

Given by FINMA

- Scenarios S_1, \dots, S_d along with auxiliary probabilities $\pi_i > 0$
 - ↪ In general, $\pi_i \neq \mathbb{P}[S_i]$
 - ↪ It is natural to set $S_0 = \Omega$ and $\pi_0 = 1 - \sum_{i=1}^d \pi_i$

Scenario	Probability of occurrence
Industrial	0.5%
Pandemic	1%
Accident on a works outing	0.5%
Accident: Panic in a football stadium	Type 2: not relevant for target capital.
Hail scenario	Type 2: not relevant for target capital.
Disability	0.5%
Daily allowance for sickness	0.5%

Source: FOPI, *SST Technical Documents*, 2006

SST Scenario Aggregation

Ansatz

- ▶ Scenario S_i causes an extra-ordinary loss

$$\ell_i = \mathbb{E}[L \mid S_i] - \mathbb{E}[L]$$

to be determined by actuary, with $\ell_0 = 0$

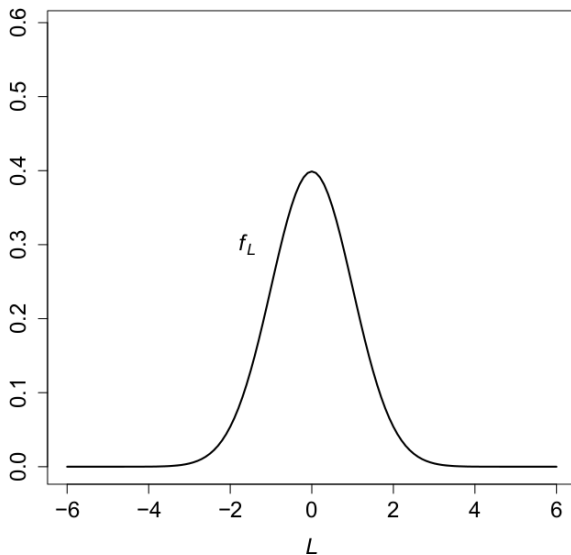
- ▶ Loss distribution conditional on scenario S_i is $F_L(x - \ell_i)$

Aggregation

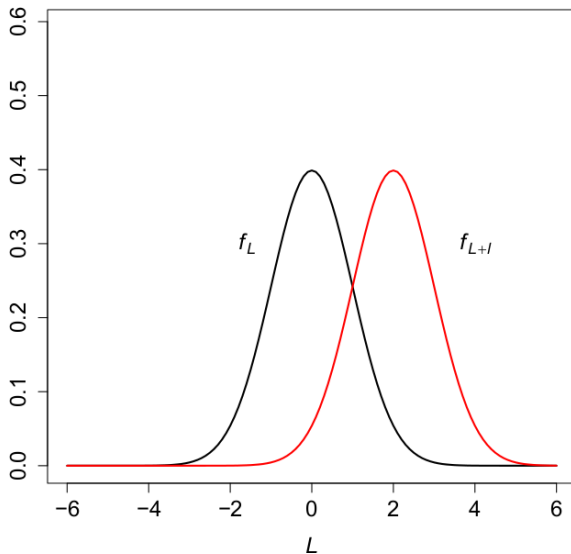
- ▶ Replace $F_L(x)$ by aggregated loss distribution

$$F_L^{\text{aggr}}(x) = \sum_{i=0}^d \pi_i F_L(x - \ell_i)$$

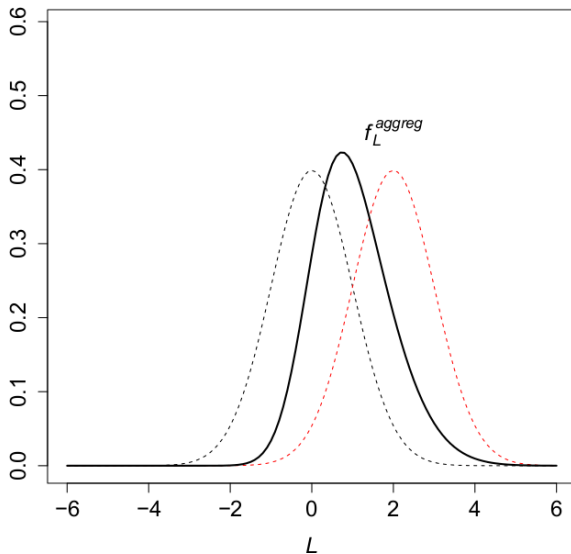
SST Scenario Aggregation



SST Scenario Aggregation



SST Scenario Aggregation



SST Method: Discussion

- ▶ Fact: $F_L^{\text{aggr}}(x)$ is the cdf of $L + Z$ for an independent extra-ordinary loss random variable Z with $\mathbb{P}[Z = \ell_i] = \pi_i$
- ▶ Lemma:

$$\text{ES}^{\text{aggr}}[L] = \text{ES}[L + Z] \geq \text{ES}[L] + \mathbb{E}[Z]$$

- ▶ Consequence: if $\mathbb{E}[Z] > 0$ then

$$\text{ES}^{\text{aggr}}[L] > \text{ES}[L]$$

no matter how conservative the internal model for L is

⇒ scenario aggregation penalizes conservative internal models

SST Method: Discussion

- ▶ No control on how far $F_L^{\text{aggr}}(x)$ from $F_L(x)$ is
- ▶ No control on how far $\text{ES}^{\text{aggr}}(L)$ from $\text{ES}(L)$ is
- ▶ Confusion among stakeholders about “double-counting”
- ▶ High degree of subjectivity about auxiliary weights π_i
- ▶ Capital is increased even if scenario is not in tail loss event
- ▶ Aggregation is on the level of $F_L(x)$, not \mathbb{P}

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A Moment's Reflection on Stress Tests

- ▶ Stress test: selected states of the world $\omega_i \in \Omega$
- ▶ Leads to a maximal insurer specific loss $\ell = \max_i L(\omega_i)$
- ▶ Internal model (null hypothesis) \mathbb{P} passes the stress test if not rejected on significance level $1 - \alpha = 1\%$. That is, if

$$\ell \leq \text{VaR}_\alpha(L)$$

- ▶ Equivalently,

$$\mathbb{P}[S] \geq 1 - \alpha$$

for the scenario $S = \{L \geq \ell\}$

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Definition of Views

- ▶ Given a collection of scenarios $S_1, \dots, S_d \in \mathcal{F}$
- ▶ Given a vector of target probabilities $\mathbf{c} = (c_1, \dots, c_d)^\top$
- ▶ Define $S_0 = \Omega \setminus \cup_{i=1}^d S_i$
- ▶ Denote \mathcal{M} = set of probability measures on (Ω, \mathcal{F})
- ▶ **Views** on $\mathbb{Q} \in \mathcal{M}$:

$$\mathbb{Q}[S_i] \geq c_i, \quad i = 1, \dots, d \quad (\text{views})$$

Views in Terms of Atoms

- ▶ Let U_0, \dots, U_n be the atoms of $\mathcal{S} = \sigma(S_1, \dots, S_d)$:

$$S_0 = U_0, \quad S_i = \cup_{j \in J(i)} U_j, \quad i = 1, \dots, d$$

- ▶ **Views** on $\mathbb{Q} \in \mathcal{M}$:

$$\sum_{j \in J(i)} q_j \geq c_i, \quad i = 1, \dots, d \quad (\text{views})$$

for vector $q_j = \mathbb{Q}[U_j]$

- ▶ **Views** in matrix form:

$$A \mathbf{q} \geq \mathbf{c} \quad (\text{views})$$

for matrix $A_{ij} = 1_{J(i)}(j)$

Scenario Aggregation

- Modification of internal model: find minimizer for

$$\begin{array}{ll}\text{minimize} & d(\mathbb{Q}, \mathbb{P}) \\ \text{subject to} & (\text{views})\end{array}$$

with domain \mathcal{M}

- $d(\cdot, \mathbb{P})$ measures the difference from \mathbb{P} on \mathcal{M}

ϕ -Divergence

- ▶ ϕ -divergence

$$d(\mathbb{Q}, \mathbb{P}) = \begin{cases} \mathbb{E}[\phi(d\mathbb{Q}/d\mathbb{P})], & \text{if } \mathbb{Q} \ll \mathbb{P} \\ +\infty, & \text{otherwise} \end{cases}$$

where ϕ is convex, and strictly convex at 1 with $\phi(1) = 0$

- ▶ Standard measure for difference of \mathbb{Q} from \mathbb{P} in statistics, Csiszar (1963)
- ▶ Fact: $d(\mathbb{Q}, \mathbb{P})$ is not a metric, but convex in \mathbb{Q}

Examples and Facts

► Examples:

$$\phi(t) = \begin{cases} t \log t, & \text{relative entropy} \\ (\sqrt{t} - 1)^2, & \text{Hellinger distance} \\ |t - 1|^p, & L^p\text{-distance, } p \geq 1 \end{cases}$$

► Facts:

$$\begin{aligned} \|d\mathbb{Q}/d\mathbb{P} - 1\|_1 &\leq \sqrt{2d_E(\mathbb{Q}, \mathbb{P})} \\ d_H(\mathbb{Q}, \mathbb{P}) &\leq \|d\mathbb{Q}/d\mathbb{P} - 1\|_1 \leq \sqrt{2d_H(\mathbb{Q}, \mathbb{P})} \\ \|d\mathbb{Q}/d\mathbb{P} - 1\|_1 &= 2 d_{TV}(\mathbb{Q}, \mathbb{P}) \quad \text{total variation} \end{aligned}$$

► Fact: all but the L^1 -distance are strictly convex in \mathbb{Q}

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Robustness Check

- ▶ Question: is the capital requirement robust under minimum ϕ -divergence scenario aggregation?
- ▶ In other words: is VaR and ES continuous with respect to $d(\mathbb{Q}, \mathbb{P})$?

Recall Definitions of VaR and ES

- ▶ Value at risk

$$\text{VaR}(X) = q_{\alpha}^{-}(X), \quad \text{left } \alpha\text{-quantile}$$

- ▶ Expected shortfall

$$\begin{aligned}\text{ES}(X) &= \frac{1}{1-\alpha} \mathbb{E}[(X - q)^+] + q \\ &= \frac{1}{1-\alpha} (\mathbb{E}[X \mathbf{1}_{\{X > q\}}] + q(\mathbb{P}[X \leq q] - \alpha))\end{aligned}$$

for any α -quantile $q \in [q_{\alpha}^{-}(X), q_{\alpha}^{+}(X)]$

- ▶ Folk theorem: VaR is more robust than ES ...

Lemma for Value at Risk

Lemma 4.1.

If $d\mathbb{P}_n/d\mathbb{P} \rightarrow 1$ in L^1 then

$$\sup_x |\mathbb{P}_n[X \leq x] - \mathbb{P}[X \leq x]| \rightarrow 0$$

and

$$q_{\alpha}^{-}(X) \leq \liminf_n q_n \leq \limsup_n q_n \leq q_{\alpha}^{+}(X)$$

for any sequence (q_n) of α -quantiles of X , for any $X \in L^0$.

Non-Robustness of Value at Risk: Example

- ▶ Define $X = 0$ or 1 with $\mathbb{P}[X = 0] = \alpha$
- ▶ Define

$$d\mathbb{P}_n/d\mathbb{P} = \begin{cases} 1 + (1 - \alpha)(-1)^n/(\alpha n), & \text{on } \{X = 0\} \\ 1 + (-1)^{n+1}/n, & \text{on } \{X = 1\} \end{cases}$$

- ▶ VaR does not converge:

$$\text{VaR}_n(X) = \begin{cases} 0 = q_{\alpha}^{-}(X), & \text{for } n \text{ even} \\ 1 = q_{\alpha}^{+}(X), & \text{for } n \text{ odd} \end{cases}$$

Robustness of Expected Shortfall

Theorem 4.2.

Let $p \in [1, \infty]$. If $d\mathbb{P}_n/d\mathbb{P} \rightarrow 1$ in L^p then

$$\text{ES}_n(X) \rightarrow \text{ES}(X)$$

for all $X \in L^r$, where $p^{-1} + r^{-1} = 1$.

Proof.

Using previous lemma and

$$\begin{aligned} (1 - \alpha) |\text{ES}_n(X) - \text{ES}(X)| &\leq \mathbb{E} [|Z_n - 1|(X - q_n)^+] \\ &\quad + \mathbb{E} [|(X - q_n)^+ - (X - q)^+|] + (1 - \alpha) |q_n - q| \end{aligned}$$

for any converging (sub-)sequence of α -quantiles $q_n \rightarrow q$. □

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Back to the Optimization Problem

- Modification of internal model: find minimizer for

$$\begin{array}{ll}\text{minimize} & d(\mathbb{Q}, \mathbb{P}) \\ \text{subject to} & (\text{views})\end{array}\tag{P}$$

with domain \mathcal{M}

Lemma 4.3.

For every $\mathbb{R} \ll \mathbb{P}$ satisfying the views there exists a

$$\mathbb{R}' \in \mathcal{Q} := \{\mathbb{Q} \ll \mathbb{P} \mid d\mathbb{Q}/d\mathbb{P} \text{ is } \mathcal{S}\text{-measurable}\}$$

satisfying the views and $d(\mathbb{R}', \mathbb{P}) \leq d(\mathbb{R}, \mathbb{P})$.

Proof.

Set $d\mathbb{R}'/d\mathbb{P} = \mathbb{E}[d\mathbb{R}/d\mathbb{P} \mid \mathcal{S}]$ and use Jensen's inequality. □

Existence and Uniqueness

- Note $\dim \mathcal{Q} = n + 1$: identify $\mathbb{Q} \in \mathcal{Q}$ with \mathbf{q} by

$$q_j = \mathbb{Q}[U_j], \quad j = 0, \dots, n$$

Theorem 4.4.

There exists a solution of (P) in \mathcal{Q} . Moreover, if ϕ is strictly convex then the solution is unique.

Solution of Optimization Problem

- ▶ Define $\mathbf{p} \in (0, 1)^{n+1}$ by $p_j = \mathbb{P}[U_j]$
- ▶ The optimization problem (P) reduces to

$$\begin{aligned} & \text{minimize} && \sum_{j=0}^n p_j \phi(q_j/p_j) \\ & \text{subject to} && A\mathbf{q} \geq \mathbf{c} \\ & && \mathbf{1}^\top \mathbf{q} = \mathbf{1} \end{aligned} \tag{P}$$

with domain $(0, 1)^{n+1}$

- ▶ Solution via dual problem or Kuhn–Tucker (FOC) conditions
- ▶ Reference e.g. Boyd and Vandenberghe (2004)

Special Case: $d = 1$ Scenario

Corollary 4.5.

For $d = 1$ scenario S_1 a (the) solution to (P) is given by

$$\frac{d\mathbb{Q}^*}{d\mathbb{P}} = \frac{1 - \max\{c_1, p_1\}}{p_0} 1_{S_0} + \frac{\max\{c_1, p_1\}}{p_1} 1_{S_1}$$

independently of the choice of the (strictly) convex divergence function ϕ .

Proof.

Convexity of ϕ implies that $q_1 \mapsto d(\mathbb{Q}(q_1), \mathbb{P})$ is non-decreasing in q_1 for $q_1 > p_1$. □

Special Case: $d = 1$ Scenario

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Proof.

Convexity of ϕ implies that $q_1 \mapsto d(\mathbb{Q}(q_1), \mathbb{P})$ is non-decreasing in q_1 for $q_1 > p_1$. □

Special Case: Stress Testing ($d = 1$ Scenario)

- ▶ Recall stress testing is equivalent to $d = 1$ views

$$\mathbb{Q}[S_1] \geq 1 - \alpha$$

on the scenario $S_1 = \{L \geq \ell\}$ with $\ell = \max_i L(\omega_i)$

- ▶ In this case we obtain a closed form expression for ES:

Corollary 4.6.

The expected shortfall under \mathbb{Q}^ given in Corollary 4.5 satisfies*

$$\text{ES}_{\mathbb{Q}^*, \alpha}(L) = \text{ES}_{\mathbb{P}, \max\{\mathbb{P}[L < \ell], \alpha\}}(L).$$

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Relative Entropy: Dual Problem

- ▶ The Lagrangian function is

$$L(\mathbf{q}, \lambda, \nu) = \sum_{j=0}^n q_j \log \frac{q_j}{p_j} + \lambda^\top (\mathbf{c} - A\mathbf{q}) + \nu (\mathbf{1}^\top \mathbf{q} - 1)$$

- ▶ The dual problem is

$$\begin{aligned} & \text{minimize} && \sum_{j=0}^n p_j e^{(A^\top \lambda)_j - \nu - 1} - \mathbf{c}^\top \lambda + \nu \\ & \text{subject to} && \lambda \geq 0 \end{aligned} \tag{DP}$$

with domain $\lambda \in \mathbb{R}^d$ and $\nu \in \mathbb{R}$

Relative Entropy: Slater's Condition

- ▶ Slater's condition: $\exists \mathbf{q} > 0$ such that $A\mathbf{q} \geq \mathbf{c}$ and $\mathbf{1}^\top \mathbf{q} = 1$
- ▶ If Slater's condition holds then there exists a unique minimizer (λ^*, ν^*) of the dual problem (DP), and strong duality holds:

$$q_j^* = p_j e^{(A^\top \lambda^*)_j - \nu^* - 1} \quad j = 0, \dots, d$$

Relative Entropy: Kuhn–Tucker Conditions

If Slater's condition holds then the Kuhn–Tucker conditions are necessary and sufficient for optimality:

$$\begin{aligned}\lambda &\geq \mathbf{0}, \quad A\mathbf{q} \geq \mathbf{c}, \quad \lambda^\top (A\mathbf{q} - \mathbf{c}) = \mathbf{0} \\ \mathbf{1}^\top \mathbf{q} &= 1 \\ \log \mathbf{q} - \log \mathbf{p} + \mathbf{1} - A^\top \lambda + \nu \mathbf{1} &= \mathbf{0}\end{aligned}$$

Relative Entropy: Explicit Solution for Disjoint Scenarios

Lemma 4.7.

If the d scenarios S_1, \dots, S_d are mutually disjoint then the unique solution to (P) is given by

$$q_j^* = \max \left\{ c_j, p_j \frac{1 - \sum_{i=k^*+1}^d c_i}{\sum_{i=0}^{k^*} p_i} \right\}$$

where k^ is the integer determined by*

$$\sum_{i=0}^{k^*+1} p_i \left(\frac{c_{k^*+1}}{p_{k^*+1}} - \frac{c_i}{p_i} \right) > 1 - \sum_{i=0}^d c_i \geq \sum_{i=0}^{k^*} p_i \left(\frac{c_{k^*}}{p_{k^*}} - \frac{c_i}{p_i} \right)$$

and we assume w.l.o.g. that $\frac{c_0}{p_0} < \dots < \frac{c_d}{p_d}$ with $c_0 := 0$.

Relative Entropy: Example

- ▶ $d = 2$ disjoint scenarios S_1, S_2
- ▶ Target probabilities $\mathbf{c} = (0.2, 0.2)^\top$

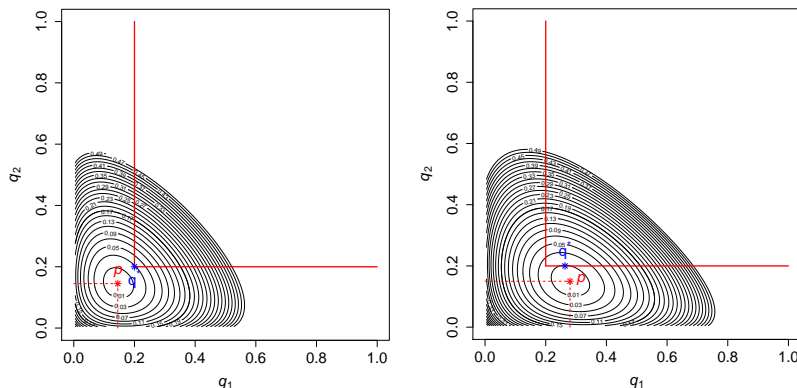


Figure: Contour plots for $(p_1, p_2)^\top \leq \mathbf{c}$ (left), $p_1 > c_1, p_2 < c_2$ (right)

Relative Entropy: More on Solutions

- ▶ In the paper we also provide explicit solutions for $d = 2$ overlapping scenarios S_1, S_2
- ▶ In general: numerical solution of dual problem

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Case Study 1: Setup

- ▶ Loss $L \sim \mathcal{N}(0, 10.2)$
- ▶ Compare scenario aggregation using SST and minimum entropy method

Case Study 1: SST Method

- ▶ $d = 1$ scenario with probability c and extra-ordinary loss ℓ
- ▶ Recall: $F_L^{\text{aggr}}(x) = (1 - c) F_L(x) + c F_L(x - \ell)$

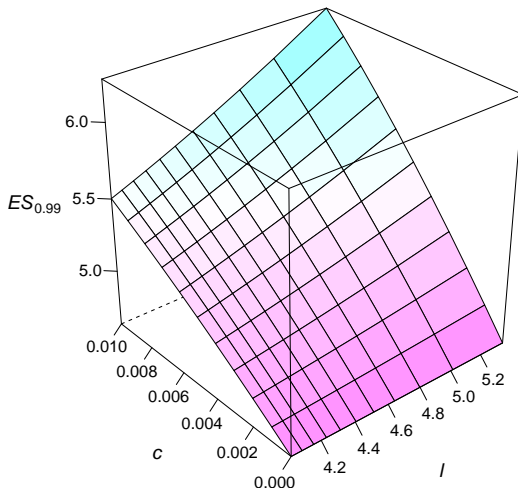


Figure: Sensitivity of $ES^{\text{aggr}}[L]$ with respect to c and ℓ

Case Study 1: Minimum Entropy Method

- ▶ $d = 1$ scenario $S_1 = \{L \geq \ell\}$
- ▶ View: $\mathbb{Q}[L \geq \ell] \geq c$ for some auxiliary level c

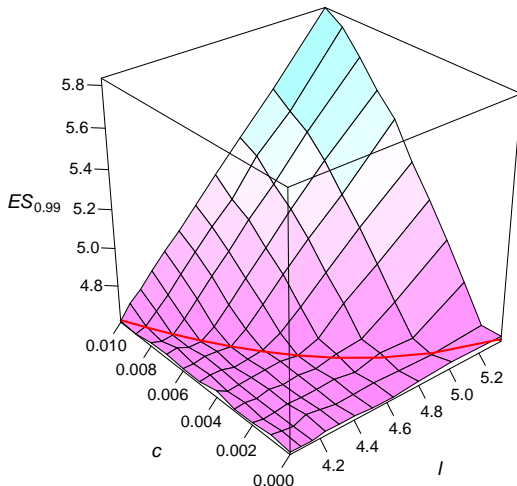


Figure: Sensitivity of $ES_{\mathbb{Q}^*}[L]$ with respect to c and ℓ

Case Study 1: Difference SST - Minimum Entropy Method

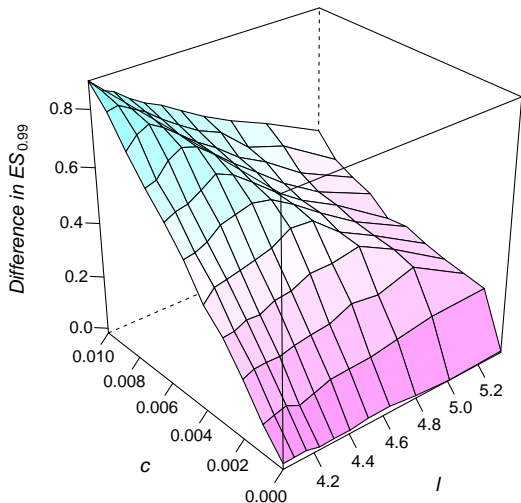


Figure: $ES^{\text{aggr}}[L] - ES_{Q^*}[L]$ as function of c and ℓ

Case Study 1 (Stress Test): Minimum Entropy Method

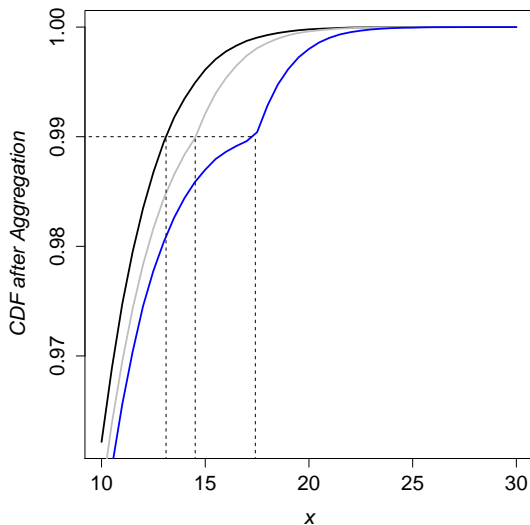


Figure: Impact on cumulative distribution function for $\ell = \text{VaR}_\alpha(L)$ with $\alpha = 0.99$ (black), $\alpha = 0.995$ (grey), $\alpha = 0.999$ (blue)

Outline

Risk-Based Solvency Regulation

Is Risk-Based Market Consistency Too Expensive?

Scenario Aggregation in the Swiss Solvency Test

Minimum ϕ -Divergence Approach

Minimum ϕ -Divergence Scenario Aggregation

Robustness of Capital Requirement

Solving the Optimization Problem

Example: Relative Entropy

Case Studies

Case Study 1

Case Study 2

Case Study 2: Setup

- ▶ Two risk factors (X_1, X_2) normal with mean $\mathbf{0}$, and $\text{var}(X_1) = 1$, $\text{var}(X_2) = 4$, and $\text{corr}(X_1, X_2) = -0.5$
- ▶ X_1 : change in interest rates
- ▶ X_2 : risk factor related to CAT events with reinsurance
- ▶ Loss

$$L = \max\{X_1, -1\} + \max\{\min\{X_2, 5\}, -1\}$$

is capped in X_2 (reinsurance), and gains are capped at 1

- ▶ $d = 2$ scenarios

$$S_1 = \{X_1 \geq 1, X_2 \geq 1\} \quad \text{and} \quad S_2 = \{X_1 < -2\}$$

Case Study 2: Shortfall Region

- ▶ Shortfall region $W = \{L > \text{VaR}_{0.99}(L)\}$ overlaps with S_1 ,

$$W \cap S_1 \neq \emptyset$$

but not with S_2 ,

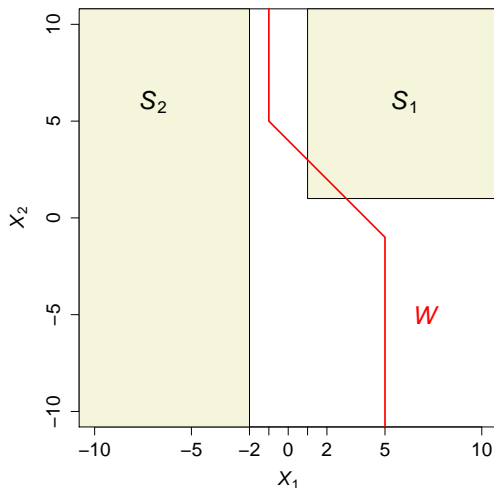
$$W \cap S_2 = \emptyset$$

- ▶ Extra-ordinary losses caused by S_1 and S_2 are positive

$$\ell_1 = \mathbb{E}[L \mid S_1] - \mathbb{E}[L] = 2.7, \quad \ell_2 = \mathbb{E}[L \mid S_2] - \mathbb{E}[L] = 0.9$$

- ▶ SST aggregation of S_2 leads to a capital increase even though S_2 does not intersect with the shortfall region W

Case Study 2: Scenarios and Shortfall Region



Case Study 2: SST Method

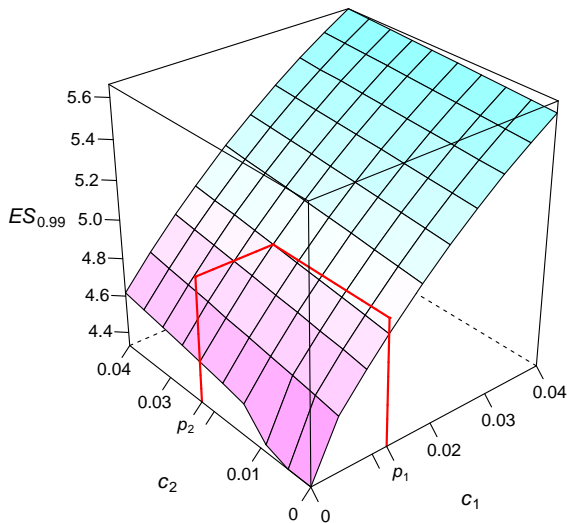


Figure: Sensitivity of $ES^{\text{aggr}}[L]$ with respect to c_1 and c_2

Case Study 2: Minimum Entropy Method

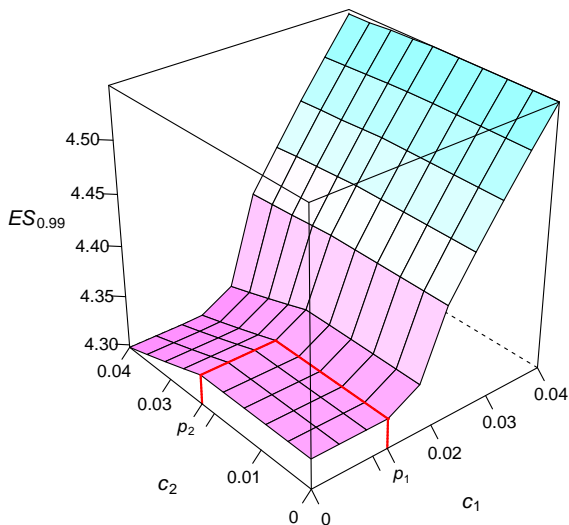


Figure: Sensitivity of $ES_{Q^*}[L]$ with respect to c_1 and c_2

Case Study 2: Difference SST - Minimum Entropy Method

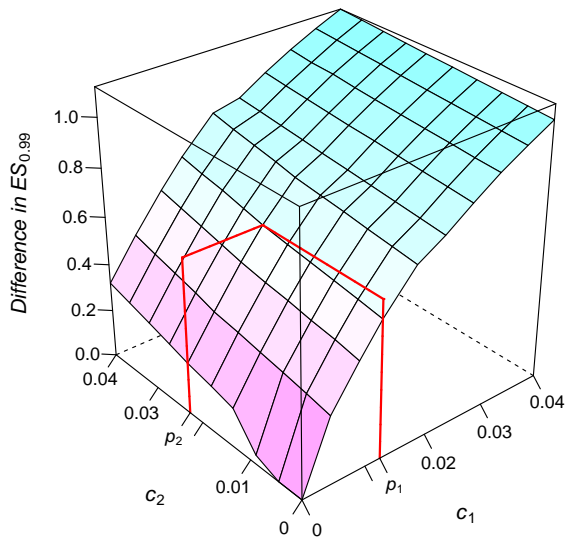


Figure: $ES^{\text{aggr}}[L] - ES_{Q^*}[L]$ as function of c_1 and c_2

Conclusion

- ▶ Risk-based market-consistent solvency regime comes along with intended and unintended consequences
- ▶ Scenario aggregation is vital part of risk-based solvency regulation
- ▶ Current SST method subject to critical review
- ▶ Minimum ϕ -divergence approach is a coherent scenario aggregation method:
 - ▶ No penalty for conservative internal models
 - ▶ Focus on tail loss events
 - ▶ Control over distance from internal model
 - ▶ Robustness of capital requirement
 - ▶ Highly tractable (closed form solutions sometimes)