

Robust consumption-investment problem over infinite horizon

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Introduction

- The aim of the investor is to maximize total expected discounted utility of consumption.

Literature:

Karatzas et al (1989), Fleming and Hernandez (2003), Fleming and Pang (2004), Hata and Sheu (2013)

- The investor believes that model is misspecified and he tries to protect against the worst scenario (the worst model) by looking for robust investment and consumption.

Literature:

Schied (2008), Trojani and Vanini (2004), Hansen et al (2006), Gagliardini et al (2009), Faria and Coreia-da-Silva (2012)

Overview

- 1 The problem
- 2 HJBI equation
- 3 Smooth solution to the resulting HJB
- 4 Final result

Financial market-reference model

- A bank account

$$dS_t^0 = r(Y_t) S_t^0 dt,$$

- An asset

$$dS_t = b(Y_t) dt + \sigma(Y_t) dB_t^1,$$

Market price of risk: $\lambda(y) = \frac{b(y) - r(y)}{\sigma(y)}$

- A non-tradable economic factor

$$dY_t = g(Y_t) dt + a(Y_t) (\rho dB_t^1 + \sqrt{1 - \rho^2} dB_t^2).$$

Robust portfolio optimization (finite horizon)

- Model risk is described by a set of probability measures \mathcal{Q}
- The investor tries to maximize a functional

$$X \rightarrow \inf_{Q \in \mathcal{Q}} \mathbb{E}^Q U(X),$$

where U is a utility function and X is a terminal wealth.

Model misspecification - finite horizon

To describe model uncertainty many authors use

$$\mathcal{Q} := \left\{ Q \sim P \mid \frac{dQ}{dP} = \mathcal{E} \left(\int \eta_{1,t} dB_t^1 + \eta_{2,t} dB_t^2 \right)_T \quad (\eta_1, \eta_2) \in \mathcal{M} \right\},$$

where $\mathcal{E}(\cdot)_T$ denotes the Doleans-Dade exponential \mathcal{M} denotes the set of all progressively measurable processes $\eta = (\eta_1, \eta_2)$ taking values in a fixed compact convex set $\Gamma \subset \mathbb{R}^2$.

Model misspecification – infinite horizon

Instead of modeling Q we consider a set of alternative market dynamics with uncertain drift:

$$\begin{cases} dS_t^0 &= r(Y_t)S_t^0 dt, \\ dS_t &= (b(Y_t) + \eta_{1,t}\sigma(Y_t))S_t dt + \sigma(Y_t)S_t dB_t^1, \\ dY_t &= (g(Y_t) + (\eta_{1,t}\rho + \eta_{2,t}\bar{\rho})a(Y_t)) dt + a(Y_t)(\rho dB_t^1 + \bar{\rho} dB_t^2). \end{cases}$$

Investor's wealth dynamics ($X_t^{\pi,c,\eta}$, $0 \leq t < +\infty$) is given by:

$$dX_t = [r(Y_t)X_t + \pi_t(b(Y_t) - r(Y_t) + \eta_{1,t}\sigma(Y_t))] dt + \pi_t\sigma(Y_t)dB_t^1 - c_t dt,$$

π - capital invested in risky asset,

c - consumption per unit of time.

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Main problem

- Objective function

$$\mathcal{J}^{\pi, \mathbf{c}, \eta}(x, y) := \mathbb{E}_{x, y} \int_0^{\tau^{\pi, \mathbf{c}, \eta}} e^{-wt} \frac{(c_t)^\gamma}{\gamma} dt. \quad 0 < \gamma < 1,$$

$$\tau^{\pi, \mathbf{c}, \eta} = \inf\{t \geq 0 : X_t^{\pi, \mathbf{c}, \eta} \leq 0\}$$

- Investor, who doubts his model, uses maxmin criterion:

$$\text{maximize} \inf_{\eta \in \mathcal{M}} \mathcal{J}^{\pi, \mathbf{c}, \eta}(x, y) \text{ over } (\pi, \mathbf{c}) \in \mathcal{A}_{x, y}.$$

- This can be considered as a zero sum stochastic differential game, where the investor is looking for a saddle point $(\pi^*, \mathbf{c}^*, \eta^*)$, that is

$$\mathcal{J}^{\pi, \mathbf{c}, \eta^*} \leq \mathcal{J}^{\pi^*, \mathbf{c}^*, \eta^*}(x, y) \leq \mathcal{J}^{\pi^*, \mathbf{c}^*, \eta}(x, y)$$

HJBI equation

- Differential operator

$$\begin{aligned} \mathcal{L}^{\pi, c, \eta} V(x, y) = & \frac{1}{2} a^2(y) V_{yy} + \frac{1}{2} \pi^2 \sigma^2(y) V_{xx} + \rho \pi \sigma(y) a(y) V_{xy} \\ & + (\rho \eta_1 + \bar{\rho} \eta_2) a(y) V_y + g(y) V_y + \pi (b(y) - r(y) + \eta_1 \sigma(y)) V_x + r(y) x V_x - c V_x. \end{aligned}$$

- We have to solve

$$\begin{aligned} & \max_{\pi \in \mathbb{R}} \max_{c > 0} \min_{\eta \in \Gamma} (\mathcal{L}^{\pi, c, \eta} V - wV + \frac{c^\gamma}{\gamma}) \\ & = \min_{\eta \in \Gamma} \max_{\pi \in \mathbb{R}} \max_{c > 0} (\mathcal{L}^{\pi, c, \eta} - wV + \frac{c^\gamma}{\gamma}) = 0. \end{aligned}$$

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Verification theorem, part I

Suppose there exists a function $V \in \mathcal{C}^{2,2}((0, +\infty) \times \mathbb{R}) \cap \mathcal{C}([0, +\infty) \times \mathbb{R})$ an admissible Markov control $(\pi^*(x, y), c^*(x, y), \eta^*(x, y))$ and constants $D_1, D_2 > 0$ such that

$$\begin{aligned} \mathcal{L}^{\pi^*(x,y), c^*(x,y), \eta} V(x, y) - wV(x, y) + \frac{(c^*(x, y))^\gamma}{\gamma} &\geq 0, \\ \mathcal{L}^{\pi, c, \eta^*(x,y)} V(x, y) - wV(x, y) + \frac{c^\gamma}{\gamma} &\leq 0, \\ \mathcal{L}^{\pi^*(x,y), c^*(x,y), \eta^*(x,y)} V(x, y) - wV(x, y) + \frac{(c^*(x, y))^\gamma}{\gamma} &= 0, \\ D_1 x^\gamma &\leq (c^*(x, y))^\gamma, \\ V(x, y) &\leq D_2 x^\gamma \end{aligned}$$

for all $\eta \in \Gamma$, $(\pi, c) \in \mathbb{R} \times (0, +\infty)$, $(x, y) \in (0, +\infty) \times \mathbb{R}$

Verification theorem, part II

and

$$\tau_{x,y}^{\pi^*, c^*, \eta} = +\infty, ,$$

$$\mathbb{E}_{x,y} \left(\sup_{0 \leq s \leq t \wedge \tau} e^{-ws} |V(X_s^{\pi, c, \eta}, Y_s)| \right) < +\infty$$

for all $(x, y) \in (0, +\infty) \times \mathbb{R}$, $t \in [0, +\infty)$, $(\pi, c) \in \mathcal{A}$, $\eta \in \mathcal{M}$.

Then

$$\mathcal{J}^{\pi, c, \eta^*}(x, y) \leq V(x, y) \leq \mathcal{J}^{\pi^*, c^*, \eta}(x, y)$$

for all $\pi \in \mathcal{A}$, $\eta \in \mathcal{M}$,

and

$$V(x, y) = \mathcal{J}^{\pi^*, c^*, \eta^*}(x, y).$$

Saddle point derivation

- Applying standard minimax results we can reduce the task to solving only one equation:

$$\min_{\eta \in \Gamma} \max_{\pi \in \mathbb{R}} \max_{c > 0} (\mathcal{L}^{\pi, c, \eta} V - wV + \frac{c^\gamma}{\gamma}) = 0,$$

- The maximum with respect to π and c is achieved at

$$\pi^*(x, y, \eta) = -\frac{\rho a(y)}{\sigma(y)} \frac{V_{xy}}{V_{xx}} - \frac{(b(y) + \eta_1 \sigma(y))}{\sigma^2(y)} \frac{V_x}{V_{xx}},$$

$$c^*(x, y) = \left(\frac{V_x}{\gamma} \right)^{\frac{1}{\gamma-1}}.$$

- The following ansatz is made:

$$V(x, y) = \frac{x^\gamma}{\gamma} F(y).$$

Transformation of HJB equation

After substitution and dividing by $\frac{x^\gamma}{\gamma}$ we get

$$\begin{aligned}
 & \frac{1}{2} a^2(y) F_{yy} + \boxed{\frac{\rho^2 \gamma}{2(1-\gamma)} a^2(y) \frac{F_y^2}{F}} + \left(g(y) + \frac{\rho \gamma}{1-\gamma} a(y) \lambda(y) \right) F_y \\
 & + \min_{(\eta_1, \eta_2) \in \Gamma} \left(\bar{\rho} \eta_2 a(y) F_y + \frac{\rho}{(1-\gamma)} a(y) \eta_1 F_y + \frac{\gamma}{2(1-\gamma)} (\lambda(y) + \eta_1)^2 F \right) \\
 & + \gamma r(y) F + \boxed{(1-\gamma) F^{\frac{-\gamma}{1-\gamma}}} - wF = 0,
 \end{aligned} \tag{2.1}$$

Transformation of HJBI equation

If there exist F solution to (2.1) and $m_1, m_2, R > 0$ such that

$$\left| \frac{F_y}{F} \right| \leq R \quad \text{and} \quad m_1 \leq F^{\frac{1}{\gamma-1}} \leq m_2,$$

then

$$\begin{aligned} \max_{q \in [-R, R]} (-Fq^2 + 2F_y q) &= \frac{F_y^2}{F}, \\ \max_{m_1 \leq c \leq m_2} \left(-\gamma c F + c^\gamma \right) &= (1 - \gamma) F^{\frac{-\gamma}{1-\gamma}}. \end{aligned}$$

Transformation of HJBI equation

Therefore it is worth to consider

$$\begin{aligned} \frac{1}{2} a^2(y) F_{yy} + \max_{q \in [-R, R]} (-Fq^2 + 2F_y q) + \min_{\eta \in \Gamma} (i(y, \eta) F_y + h(y, \eta) F) \\ + \max_{m_1 \leq c \leq m_2} (-\gamma c F + c^\gamma) - wF = 0, \end{aligned}$$

HJB equation

This equation can be generalized to

$$\frac{1}{2}a^2(y)u_{yy} + \max_{\eta \in D} \left(i(y, \eta)u_y + h(y, \eta)u \right) + \max_{c > 0} \left(-\gamma cu + c^\gamma \right) - wu = 0,$$

where $D \subset \mathbb{R}^n$ is a compact set.

Assumption 1

a, h, i are continuous functions, $a(y) > \varepsilon > 0$ and there exist constants $L_1 > 0$, $L_2 \geq 0$ such that

$$|h(y, \eta) - h(\bar{y}, \eta)| + |i(y, \eta) - i(\bar{y}, \eta)| \leq L_1|y - \bar{y}|,$$

$$|h(y, \eta)| + |a(y)|^2 \leq L_1, \quad |i(y, \eta)| \leq L_1(1 + |y|),$$

$$(y - \bar{y})(i(y, \eta) - i(\bar{y}, \eta)) + |a(y) - a(\bar{y})|^2 \leq L_2|y - \bar{y}|^2.$$

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Existence and uniqueness

Theorem

Suppose that **Assumption 1** is satisfied with $L_1 > 0$, $L_2 \geq 0$ and $w > \sup_{\eta, y} h(y, \eta) + L_2$. Then there exists a unique bounded solution to

$$\frac{1}{2} a^2(y) u_{yy} + \max_{\eta \in D} (i(y, \eta) u_y + h(y, \eta) u) + \max_{m_1 \leq c \leq m_2} (-\gamma c u + c^\gamma) - w u = 0,$$

which, in addition, has bounded y -derivative and is bounded away from zero.

Sketch of the proof

- Solution to infinite time HJB is approximated by solution to finite time horizon HJB of the form

$$u_t + \frac{1}{2} a^2(y) u_{yy} + \max_{\eta \in D} (i(y, \eta) u_y + h(y, \eta) u) + \max_{m_1 \leq c \leq m_2} (-\gamma c u + c^\gamma) - w u = 0,$$

with terminal condition $u(y, T) = 0$.

- Rubio (2012) result ensures that under Assumption 1 a unique bounded solution exists (u^T)
Related results: Friedman (1973), Pham (2002)

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- Stochastic control representation:

$$u^T(y, t) = \max_{\eta \in \mathcal{M}, c \in \mathcal{C}_{m_1, m_2}} \mathbb{E}_{y, t} \left(\int_t^T e^{\int_t^s (h(Y_k, \eta_k) - \gamma c_k - w) dk} c_s^\gamma ds \right),$$

$$dY_t = i(Y_t, \eta_t) dt + a(Y_t) dB_t,$$

Sketch of the proof

- Our equation can be rewritten as

$$u_t + \frac{1}{2} a^2(y) u_{yy} + H(y, u, u_y) = 0,$$

where

$$H(y, u, p) = \max_{\eta \in \Gamma} \left(i(y, \eta) p + h(y, \eta) u \right) + \max_{m_1 \leq c \leq m_2} \left(-\gamma c u + c^\gamma \right)$$

-

$$\begin{aligned} u^T(y, t) &= \mathbb{E}_{y,t} \int_t^T e^{-w(s-t)} H(Y_s, u^T(Y_s), u_y^T(Y_s)) ds \\ &= \mathbb{E}_{y,t} \left(\int_t^T e^{-w(s-t)} H(Y_s, u^T(Y_s), u_y^T(Y_s)) ds \right), \end{aligned}$$

where $dY_t = a(Y_t) dB_t$.

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where $dY_t = a(Y_t) dB_t$.

Sketch of the proof

- $v(y, t) := u^T(y, T - t)$
- v satisfies

$$v_t - \frac{1}{2} a^2(y) v_{yy} - H(y, u, u_y) + wv = 0$$

- passing $t \rightarrow \infty$ and using stochastic representation to estimate uniform bounds for v , v_t , v_y , we may define the solution as

$$\hat{v}(y) = \lim_{t \rightarrow \infty} v(y, t) \quad (\text{Arzel-Ascoli Lemma})$$

Non-linearity recovering

Let $F^{m_1, m_2, R}$ be the unique solution to

$$\begin{aligned} \frac{1}{2} a^2(y) F_{yy} + \max_{q \in [-R, R]} (-\theta a^2(y) F q^2 + 2\theta a^2(y) F_y q) \\ + \max_{\eta \in D} (i(y, \eta) F_y + h(y, \eta) F) + \max_{m_1 \leq c \leq m_2} (-\gamma c F + c^\gamma) - w F = 0, \end{aligned}$$

We can use infinite horizon stochastic control representation

$$F^{m_1, m_2, R}(y) = \max_{c \in C_{m_1, m_2}, q \in Q_R} \mathbb{E}_{y, 0} \left(\int_0^{+\infty} e^{\int_0^s (h(Y_k, \eta_k^*) - \theta q_k^2 - \gamma c_k - w) dk} (c_s^*)^\gamma ds \right)$$

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Non-linearity recovering

- Using stochastic representation we can find $m_1^*, m_2^*, R^* > 0$ that

$$\max_{q \in [-R^*, R^*]} (-F^* q^2 + 2F_y^* q) = \frac{(F_y^*)^2}{F^*},$$

$$\max_{m_1 \leq c \leq m_2} (-\gamma c F^* + c^\gamma) = (1 - \gamma)(F^*)^{\frac{-\gamma}{1-\gamma}},$$

where $F^* = F^{m_1^*, m_2^*, R^*}$

- This implies that F^* is a solution to

$$\begin{aligned} & \frac{1}{2} a^2(y) F_{yy} + \frac{\rho^2 \gamma}{2(1-\gamma)} a^2(y) \frac{F_y^2}{F} \\ & + \max_{\eta \in D} (i(y, \eta) F_y + h(y, \eta) F) + (1-\gamma) F^{\frac{-\gamma}{1-\gamma}} - wF = 0. \quad (4.1) \end{aligned}$$

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final result






Theorem

Suppose that a, g, r, λ are Lipschitz continuous functions, a, λ, r are bounded and $a(y) > \varepsilon > 0$, g is of linear growth, $w > \sup_{\eta, y} h(y, \eta) + L_2$. Then there exists a saddle point $(\pi^*(x, y), c^*(x, y), \eta^*(x, y))$ such that





$$\pi^*(x, y) = \frac{\rho a(y)x}{(1-\gamma)\sigma(y)} \frac{F_y}{F} + \frac{(\lambda(y) + \eta_1^*(y))x}{(1-\gamma)\sigma(y)}, \quad c^*(x, y) := \left(\frac{F}{\gamma}\right)^{\frac{1}{\gamma-1}} x$$

where F is a bounded together with y -derivative and bounded away from zero solution to (4.1). η^* is a Borel measurable function which realizes maximum in (4.1).




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Thank you for your
attention.