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Linear processes

S-topology

When *S* is a useful tool?

Genesis of *S*-topology

 $(\mathbb{D}, S)$  as LTS

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## S-topology on the Skorokhod space Recent developments and complements

6th International Conference on Stochastic Analysis and its Applications Będlewo, September 13, 2012

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Genesis of S-topology

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•  $\mathbb{D} = \mathbb{D}([0,1]:\mathbb{R}^1)$  is the set of functions  $x:[0,1] \to \mathbb{R}^1$  which are right-continuous

$$\forall_{t\in[0,1)}x(t)=x(t+),$$

and admit limits from the left

$$\forall_{t\in(0,1]}\exists x(t-).$$



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If ||x||<sub>∞</sub> = sup<sub>t∈[0,1]</sub> |x(t), then (D, || · ||<sub>∞</sub>) is a Banach space, but non-separable.



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D = D([0,1]: R<sup>1</sup>) is the set of functions
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- If ||x||<sub>∞</sub> = sup<sub>t∈[0,1]</sub> |x(t), then (D, || · ||<sub>∞</sub>) is a Banach space, but non-separable.
- Skorokhod (1956) introduced 4 separable metric topologies on D, with J₁ and M₁ the most important and finding many applications. In particular (D, J₁) is a Polish space.



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- Skorokhod (1956) introduced 4 separable metric topologies on D, with J₁ and M₁ the most important and finding many applications. In particular (D, J₁) is a Polish space.
- It must be emphasized that Skorokhod's topologies are non-linear, hence practically useless in handling e.g. minimization problems. Contrary to the case of (ℂ, || · ||∞), there is no analysis on (D, J<sub>1</sub>)!

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Linear processes

S-topology

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Genesis of S-topology

Let

*α* ∈ (0, 2)

and  $\{\xi_j\}_{j\in\mathbb{Z}}$  be an i.i.d sequence with marginal distribution satisfying

$$P(|\xi_j| > x) = x^{-\alpha}h(x), \ x > 0,$$
$$\lim_{x \to \infty} \frac{P(Y > x)}{P(|Y| > x)} = p \quad \text{and} \quad \lim_{x \to \infty} \frac{P(Y < -x)}{P(|Y| > x)} = q$$
for some  $p \ge 0$  and  $q \ge 0$  with  $p + q = 1$ .

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Linear processes

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for some  $p \ge 0$  and  $q \ge 0$  with p + q = 1. This means that under additional assumptions ( $E\xi_j = 0$  if  $\alpha \in (1, 2)$  and if  $\xi_j$  are symmetric if  $\alpha = 1$ ) there exists a sequence  $B_n \to \infty$  such that

$$\frac{\xi_1+\xi_2+\ldots+\xi_n}{B_n} \xrightarrow{\mathcal{D}} \mu,$$

where  $\mu$  is a non-degenerate strictly  $\alpha$ -stable distribution.

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Linear processes

S-topology

When *S* is a useful tool?

Genesis of *S*-topology

(**D**, *S*) as LTS

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Linear processes

S-topology

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A linear process built on  $\{\xi_i\}$  is of the form

$$X_i = \sum_{j \in \mathbb{Z}} c_j \xi_{i-j}, \quad i \in \mathbb{Z},$$

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A linear process built on  $\{\xi_i\}$  is of the form

$$X_i = \sum_{j \in \mathbb{Z}} c_j \xi_{i-j}, \quad i \in \mathbb{Z},$$

Observe that a big value of  $\xi_i$  propagates along  $X_i$ 's.

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Observe that a big value of  $\xi_j$  propagates along  $X_j$ 's. Assume that

$$\sum_{j\in\mathbb{Z}}|\mathcal{C}_j|<+\infty.$$

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Linear processes

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Observe that a big value of  $\xi_j$  propagates along  $X_j$ 's. Assume that

$$\sum_{j\in\mathbb{Z}}|\boldsymbol{c}_j|<+\infty.$$

Under some assumptions on  $\{c_k\}$  one can prove that for each t > 0

$$\widetilde{X}_n(t) = rac{1}{B_n} \sum_{i=1}^{[nt]} X_i \quad \longrightarrow \quad AZ_t$$

where  $A = \sum_{j \in \mathbb{Z}} c_j$  and  $\{Z_t\}$  is a stable Lévy motion such that  $Z_1 \sim \mu$ .

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where  $A = \sum_{j \in \mathbb{Z}} c_j$  and  $\{Z_t\}$  is a stable Lévy motion such that  $Z_1 \sim \mu$ . In fact we have the finite dimensional convergence of  $X_n$  to Z.

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Linear processes

S-topology

When *S* is a useful ool?

Genesis of *S*-topology

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Linear processes

S-topology

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Avram and Taqqu (1992) observed that in general  $X_n$ 's does not converge to Z in Skorokhod's  $J_1$  topology.

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S-topology

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They were able to prove that if

$$c_k \ge 0, \ k \in \mathbb{Z}_{2}$$

then

$$X_n \xrightarrow{\mathcal{D}} Z$$

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Linear processes

S-topology

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Question: is there any functional topology on  $\mathbb{D}$  such that  $X_n$ 's are convergent to Z in this topology without additional assumptions on the nature of  $\{c_k\}$ ?

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Linear processes

S-topology

When *S* is a useful tool?

Genesis of S-topology

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 Let V ⊂ D be the space of (regularized) functions of finite variation on [0, 1], equipped with the norm of total variation ||v|| = ||v||(1), where

$$\|v\|(t) = \sup \Big\{ |v(0)| + \sum_{i=1}^{m} |v(t_i) - v(t_{i-1})| \Big\},$$

and the supremum is taken over all partitions  $0 = t_0 < t_1 < \ldots < t_m = t$ .

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Linear processes

S-topology

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and the supremum is taken over all partitions  $0 = t_0 < t_1 < \ldots < t_m = t$ .

Since V can be identified with a dual of (C, || · ||<sub>∞</sub>), we have on it the weak-\* topology. We shall write v<sub>n</sub> ⇒ v<sub>0</sub> if for every f ∈ C([0, 1] : R<sup>1</sup>)

$$\int_{[0,1]} f(t) dv_n(t) \to \int_{[0,1]} f(t) dv_0(t).$$

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S-topology

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Genesis of S-topology

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### Definition

We shall write  $x_n \to_S x_0$  if for every  $\varepsilon > 0$  one can find elements  $v_{n,\varepsilon} \in \mathbb{V}$ , n = 0, 1, 2, ... which are  $\varepsilon$ -uniformly close to  $x_n$ 's and weakly-\* convergent:

$$\begin{aligned} \|x_n - v_{n,\varepsilon}\|_{\infty} &\leq \varepsilon, \qquad n = 0, 1, 2, \dots, \\ v_{n,\varepsilon} \Rightarrow v_{0,\varepsilon}, \qquad \text{as } n \to \infty. \end{aligned}$$

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S-topology

(1) (2)

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This definition as well as many properties of *S*-topology were given in:

A. J., A non-Skorohod topology on the Skorohod space, Electron. J. Probab. **2 (1997)**, paper no 4, 1–21.

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Genesis of S-topology

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S-topology

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 For a < b, let N<sup>b</sup><sub>a</sub>(x) be the number of up-crossings of levels a < b by x on [0, 1].</li> Skorokhod space

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Linear processes

S-topology

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- For a < b, let N<sup>b</sup><sub>a</sub>(x) be the number of up-crossings of levels a < b by x on [0, 1].</li>
- For η > 0, let N<sub>η</sub>(x) be the number of η-oscillations of x on [0, 1].

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S-topology

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- For *a* < *b*, let  $N_a^b(x)$  be the number of up-crossings of levels *a* < *b* by *x* on [0, 1].
- For η > 0, let N<sub>η</sub>(x) be the number of η-oscillations of x on [0, 1].

### Equivalent criteria of compactness

Let  $K \subset \mathbb{D}$  and suppose that

$$\sup_{x\in K}\|x\|_{\infty}<+\infty. \tag{3}$$

Then the statements (i) and (ii) below are equivalent: (i) For each a < b

$$\sup_{x\in K} N^{a,b}(x) < +\infty. \tag{4}$$

(ii) For each  $\eta > 0$ 

$$\sup_{x\in K} N_\eta(x) < +\infty.$$

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(5)

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### Equivalent criteria of compactness - continued

Moreover, either set of conditions (3)+(4) and (3)+(5) is equivalent to (iii) For each  $\varepsilon > 0$  and for each  $x \in K$  there exists  $v_{x,\varepsilon} \in \mathbb{V}$  such that

$$\sup_{x\in\mathcal{K}}\|x-v_{x,\varepsilon}\|_{\infty}\leqslant\varepsilon,$$

and

$$\sup_{x\in K} \|v_{x,\varepsilon}\|(1) < +\infty.$$

(iv) *K* is relatively compact with respect to *S*-topology

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(6)

(7)

## S-topology and pointwise convergence

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S-topology

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Genesis of S-topology

## S-topology and pointwise convergence

### Corollary

If  $x_n \to_S x_0$ , then in each subsequence  $\{x_{n_k}\}$  one can find a further subsequence  $\{x_{n_{k_l}}\}$  and a countable set  $D \subset [0, 1)$  such that

$$x_{n_{k_l}}(t) \rightarrow x_0(t), \quad t \in [0,1] \setminus D.$$

This gives the lower semicontinuity of many useful functionals on  $\mathbb{D}$ .

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Linear processes

S-topology

When *S* is a useful tool?

Genesis of *S*-topology

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### Remark

If  $t \in [0, 1)$ , then the evaluation at point t

$$\mathbb{D} \ni \mathbf{x} \mapsto \pi_t(\mathbf{x}) = \mathbf{x}(t)$$

is nowhere *S*-continuous.

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## A typical phenomenon for S-converegnce

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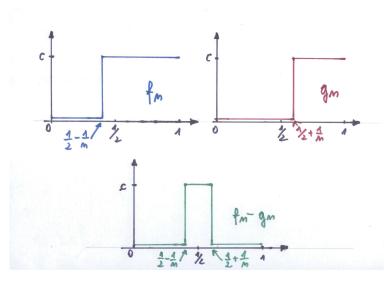
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S-topology

When *S* is a useful tool?

Genesis of S-topology

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Linear processes

### S-topology

When *S* is a useful tool?

Genesis of *S*-topology

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A summary on the S-topology

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Linear processes

S-topology

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Genesis of S-topology

This is a weak topology on  $\mathbb{D}$ , which is non-Skorokhod, sequential, not metrisable, but being submetric it is still good enough to build a satisfactory theory of the convergence in distribution. Skorokhod space

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Linear processes

S-topology

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This is a weak topology on  $\mathbb{D}$ , which is non-Skorokhod, sequential, not metrisable, but being submetric it is still good enough to build a satisfactory theory of the convergence in distribution.

In particular:

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Linear processes

S-topology

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This is a weak topology on  $\mathbb{D}$ , which is non-Skorokhod, sequential, not metrisable, but being submetric it is still good enough to build a satisfactory theory of the convergence in distribution.

In particular:

 The *σ*-field B<sub>S</sub> of Borel subsets for S coincides with the usual *σ*-field generated by projections (or evaluations) on D: B<sub>S</sub> = σ(π<sub>t</sub> : t ∈ [0, 1]). Skorokhod space

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Linear processes

S-topology

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- The set P(D, S) of S-tight probability measures is exactly the set of distributions of stochastic processes with trajectories in D: P(D, S) = P(D).

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Linear processes

S-topology

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- The set P(D, S) of S-tight probability measures is exactly the set of distributions of stochastic processes with trajectories in D: P(D, S) = P(D).
- S is a submetric topology, for there exists a countable family of S-continuous functions which separate points in D. In particular, compact subsets of (D, S) are metrisable.

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Linear processes

S-topology

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- S is a submetric topology, for there exists a countable family of S-continuous functions which separate points in D. In particular, compact subsets of (D, S) are metrisable.
- *S* is weaker than Skorohod's *J*<sub>1</sub>-topology (and even than *M*<sub>1</sub>-topology).

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Linear processes

S-topology

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Genesis of S-topology

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Linear processes

S-topology

When *S* is a useful tool?

Genesis of S-topology

•  $K \subset \mathbb{D}$  is *S*-relatively compact iff

$$\begin{split} \sup_{x\in \mathcal{K}} \sup_{t\in [0,1]} |x(t)| &\leqslant \quad \mathcal{C}_{\mathcal{K}} < +\infty, \\ \sup_{x\in \mathcal{K}} \mathcal{N}_{\eta}(x) &\leqslant \quad \mathcal{C}_{\eta} < +\infty, \; \eta > 0. \end{split}$$

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Linear processes

S-topology

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A family {X<sub>α</sub>} of stochastic processes with trajectories in D is uniformly *S*-tight iff {||X<sub>α</sub>||<sub>∞</sub>} is a uniformly tight family as well as for each η > 0 {N<sub>η</sub>(X<sub>α</sub>)} is uniformly tight.

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Linear processes

S-topology

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- How to deal with convergence in distribution with respect to the *S*-topology?

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Linear processes

S-topology

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•  $K \subset \mathbb{D}$  is *S*-relatively compact iff

$$\begin{split} \sup_{x\in K} \sup_{t\in [0,1]} |x(t)| &\leqslant \quad \mathcal{C}_{\mathcal{K}} < +\infty, \\ \sup_{x\in \mathcal{K}} \mathcal{N}_{\eta}(x) &\leqslant \quad \mathcal{C}_{\eta} < +\infty, \; \eta > 0. \end{split}$$

- A family {X<sub>α</sub>} of stochastic processes with trajectories in D is uniformly *S*-tight iff {||X<sub>α</sub>||<sub>∞</sub>} is a uniformly tight family as well as for each η > 0 {N<sub>η</sub>(X<sub>α</sub>)} is uniformly tight.
- How to deal with convergence in distribution with respect to the *S*-topology?

### Theorem, A.J. '97

Suppose  $\{X_n\}$  is uniformly *S*-tight. Then in each subsequence  $\{X_{n_k}\}_{k\in\mathbb{N}}$  one can find a further subsequence  $\{X_{n_{k_l}}\}_{l\in\mathbb{N}}$  admitting the usual a.s. Skorohod representation on  $([0, 1], \mathcal{B}_{[0,1]})!$ 

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Linear processes

S-topology

When *S* is a useful tool?

Genesis of S-topology

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A typical application of S consists in

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A typical application of S consists in

• verifying the criteria of compactness,



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A typical application of S consists in

- verifying the criteria of compactness,
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- by passing to the limit deducing the existence of a stochastic process with desired properties and trajectories in D.





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A typical application of S consists in

- verifying the criteria of compactness,
- finding a convergent subsequence,
- by passing to the limit deducing the existence of a stochastic process with desired properties and trajectories in D.

A standard procedure when using any weak topology!

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Selected recent publications including such type of reasoning:

- K. Bahlali, A. Elouaflin, E. Pardoux, Homogenization of semilinear PDEs with discontinuous averaged coefficients, Electron. J. Probab., **14 (2009)**, 477–499.
- R. Rhodes, Stochastic Homogenization of Reflected Stochastic Differential Equations, Electron. J. Probab., 15 (2010), 989–1023.
- É. Pardoux, A.B. Sow, Homogenization of a periodic degenerate semilinear elliptic PDE, Stoch. Dyn. 11 (2011), 475–493.
- H-W. Kang, T. Kurtz, Separation of time-scales and model reduction for stochastic reaction networks, to appear in: Ann. Appl. Probab. (2012+)

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In

A. J., Towards a general Doob-Meyer decomposition theorem, Probab. Math. Statist. **26 (2006)**, 143–153,

S-topology was used in a different manner.

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In

A. J., Towards a general Doob-Meyer decomposition theorem, Probab. Math. Statist. **26 (2006)**, 143–153,

S-topology was used in a different manner.

In this paper the predictable compensator in the Doob-Meyer decomposition is obtained as a limit of

$$\widetilde{A}_t^N = \frac{1}{N} \sum_{n=1}^N A_t^n$$

which cannot be, in general, convergent in any of Skorokhod's topologies.

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S-topology

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Genesis of S-topology

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S-topology

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Another crucial step consists in obtaining the convergence of integrals

$$\int_0^T \widetilde{A}_t^N \, dC_t,$$

where  $C_t$  is the predictable compensator of the process  $l(\tau \leq t)$ , for some totally inaccessible stopping time.

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Linear processes

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Notice that  $C_t$  is continuous, but not necessarily absolutely continuous.

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Hence almost sure convergence with respect to the Lebesgue measure is useless

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S-topology

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Genesis of S-topology

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When *S* is a useful tool?

Genesis of S-topology

 Meyer and Zheng (1984) considered on D so-called "pseudo-path" topology. Convergence of sequences in this topology is just the convergence in Lebesgue measure.



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- Meyer and Zheng (1984) considered on D so-called "pseudo-path" topology. Convergence of sequences in this topology is just the convergence in Lebesgue measure.
- This topology is not suitable for the "functional convergence" of stochastic processes, for it is easy to find a sequence {x<sup>n</sup>} ⊂ D which converges in measure to x<sup>0</sup> ≡ 0 and is such that x<sup>n</sup>(q) → 1 for each rational q ∈ [0, 1].

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- Meyer and Zheng (1984) considered on D so-called "pseudo-path" topology. Convergence of sequences in this topology is just the convergence in Lebesgue measure.
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- However, as a weak topology it can be and it is used in existence problems, due to easy-to-check compactness criteria.

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• The point is that the easy compactness criteria imply much more.

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Linear processes

S-topology

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- First they imply criteria of compactness for *S*-topology (but are much stronger).



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- The point is that the easy compactness criteria imply much more.
- First they imply criteria of compactness for *S*-topology (but are much stronger).
- Second, it can be shown that S-relative compactness implies convergence in L<sup>p</sup>(μ) for each p ∈ (0,∞) and each atomless measure μ on [0, 1]

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# Meyer-Zheng topology and S-topology

- The point is that the easy compactness criteria imply much more.
- First they imply criteria of compactness for *S*-topology (but are much stronger).
- Second, it can be shown that S-relative compactness implies convergence in L<sup>p</sup>(μ) for each p ∈ (0,∞) and each atomless measure μ on [0, 1]
- The problem what the criteria of compactness considered by Meyer and Zheng really imply was investigated by T. Kurtz (1991).

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Genesis of

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- The Skorokhod space
- Linear processes
- S-topology
- When *S* is a useful tool?
- Genesis of S-topology
- $(\mathbb{D}, S)$  as LTS

It is not known whether (D, S) is a linear topological space, but addition is jointly sequentially continuous (does not mean continuous with respect to the product topology!).

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Linear processes

S-topology

When *S* is a useful tool?

Genesis of S-topology

- It is not known whether (D, S) is a linear topological space, but addition is jointly sequentially continuous (does not mean continuous with respect to the product topology!).
- In particular, we do not know whether (D, S) is a completely regular topological space.

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S-topology

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- It is not known whether (D, S) is a linear topological space, but addition is jointly sequentially continuous (does not mean continuous with respect to the product topology!).
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### Theorem

There exists a locally convex linear topology  $\tilde{S}$  on  $\mathbb{D}$  such that the sequential topology generated by  $\tilde{S}$  coincides with S.

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### Theorem

There exists a locally convex linear topology  $\hat{S}$  on  $\mathbb{D}$  such that the sequential topology generated by  $\hat{S}$  coincides with *S*.

### Conjecture

The topology  $\tilde{S}$  is the finest among all locally convex topologies on  $\mathbb{D}$ , which are coarser than the  $J_1$  topology.

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S-topology

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Genesis of S-topology

We define the topology  $\tilde{\mathcal{S}}$  by a convex basis consisting of all sets of the form

$$\alpha U + \bigcup_{n=1}^{\infty} V_1^* \cap V + V_2^* \cap 2V + \ldots + V_n^* \cap nV,$$

where

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S-topology

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$$U = \{x \in \mathbb{D}; \|x\|_{\infty} \leq 1\} \subset \mathbb{D}$$

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Linear processes

S-topology

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Linear processes

S-topology

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α > 0.

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- α > 0.
- $V_1^*, V_2^*, \dots$  are weak-\* open neighbourhoods of  $0 \in \mathbb{V}$ .

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Linear processes

S-topology

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The idea goes back to Wiweger (1959), but it is worth to emphasize that among dozens of topologies considered in sixties and seventieth there is no scheme corresponding to our space  $(\mathbb{D}, \tilde{S})$ )

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Genesis of S-topology