## Semilinear obstacle problem with measure data and generalized reflected BSDE

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Let $D \subset \mathbb{R}^{d}(d \geq 2)$ be a bounded domain, $D_{T}=[0, T] \times D$. We consider the problem

$$
\left\{\begin{array}{l}
\frac{\partial u}{\partial t}+A u=-f(\cdot, u)-\mu \text { on }\left\{h_{1}<u<h_{2}\right\},  \tag{*}\\
h_{1} \leq u \leq h_{2}, \\
u(T, \cdot)=\varphi, \quad u(t, \cdot)_{\mid \partial D}=0, \quad t \in(0, T),
\end{array}\right.
$$

where $A$ is a uniformly elliptic operator of the form

$$
A=\sum_{i, j=1}^{d}\left(\frac{\partial}{\partial x_{j}}\left(a_{i j}(t, x) \frac{\partial}{\partial x_{i}}\right)\right.
$$

and

- $f: D_{T} \times \mathbb{R} \rightarrow \mathbb{R}, \varphi: D \rightarrow \mathbb{R}$ - measurable functions satisfying some conditions (to be specified later on), $\mu$ is a bounded smooth measure on $D_{T}$,
- $h_{1}, h_{2}: D_{T} \rightarrow \overline{\mathbb{R}}$ are measurable functions such that $h_{1} \leq h_{2}$ a.e..

Problem: solve (*) for

- measurable barriers $h_{1}, h_{2}$,
- $\varphi \in L^{1}(D), f$ satisfying the monotonicity condition in $u$ (for instance $f(x, u)=-|u|^{q-1} u$ for some $\left.q>1\right)$ and mild integrability conditions,
- $\mu \in \mathcal{M}_{0, b}\left(\mathcal{M}_{0, b}\right.$ - space of all smooth signed measures on $D_{T}$ with bounded total variation (for instance $\mu(d t d x)=g d t d x$ for some $g \in L^{1}\left(D_{T}\right)$ ).

Known results for irregular barriers:

- M. Pierre $(1979,1980)$ - linear case $(f=f(x))$ with $L^{2}$ data (i.e. $\varphi, f, g \in L^{2}$ ).
- T. Klimsiak (2012) - $y \mapsto f(x, y)$ satisfies the Lipschitz condition and the linear growth condition, $L^{2}$ data (i.e. $\left.\varphi, f(\cdot, 0), g \in L^{2}\right)$.


## Cauchy-Dirichlet problem

Let

$$
f_{u}=f(\cdot, u)
$$

We first consider the problem

$$
\left\{\begin{array}{l}
\frac{\partial u}{\partial t}+A u=-f_{u}-\mu \text { on }(0, T) \times D, \\
u(T, \cdot)=\varphi, \quad u(t, \cdot)_{\mid \partial D}=0, \quad t \in(0, T) .
\end{array}\right.
$$

## Cauchy-Dirichlet problem

$\mathbb{X}=\left\{\left(X, P_{s, x}\right)\right\}$ - Markov family associated with $A$.

## Proposition

Any $\mu \in \mathcal{M}_{0, b}^{+}$admits a unique positive $A F A^{\mu}$ of $\mathbb{X}$ such that for q.e. $(s, x) \in D_{T}$,

$$
E_{s, x} \int_{s}^{T} f\left(t, X_{t}\right) d A_{s, t}^{\mu}=\int_{s}^{T} \int_{D} f(t, y) p(s, x, t, y) d \mu(t, y)
$$

for every positive Borel function $f: D_{T} \rightarrow \mathbb{R}$.
Here $p$ is the transition density for $\mathbb{X}$ (weak fundamental solution for $A$ ).
Ex. If $\mu(d t, d x)=g(t, x) d t d x$ for some $g \in L^{1}\left(D_{T}\right)$ then

$$
A_{s, t}^{\mu}=\int_{s}^{t} g\left(\theta, X_{\theta}\right) d \theta
$$

## Cauchy-Dirichlet problem

Assumptions.
(H1) $\mu \in \mathcal{M}_{0, b}\left(D_{T}\right)$,
(H2) $\varphi \in L^{1}(D)$,
(H3) $f:[0, T] \times D \times \mathbb{R} \rightarrow \mathbb{R}$ is a measurable function such that
(a) $y \mapsto f(t, x, y)$ is continuous for q.e. $(t, x) \in D_{T}$.
(b) There exists $\mu \in \mathbb{R}$ such that

$$
\left(f(t, x, y)-f\left(t, x, y^{\prime}\right)\right)\left(y-y^{\prime}\right) \leq \mu\left|y-y^{\prime}\right|^{2} \text { for every }
$$

$$
y, y^{\prime} \in \mathbb{R} \text { and a.e. }(t, x) \in D_{T}
$$

(c) $f(\cdot, \cdot, 0) \in L^{1}\left(D_{T}\right)$,
(d) $\forall_{c>0}(t, x) \mapsto \sup _{|y| \leq c}|f(t, x, y)| \in L^{1}\left(D_{T}\right)$.

## Cauchy-Dirichlet problem - main result

Let

$$
\xi_{s}=\inf \left\{t \geq s: X_{t} \notin D\right\}
$$

## Theorem (T. Klimsiak, A.R.)

Assume (H1)-(H3). Then there exists a unique renormalized solution $u$ of $(* *)$. Moreover,

$$
\begin{gathered}
u(s, x)=E_{s, x}\left\{\mathbf{1}_{\left\{\xi_{s}>T\right\}} \varphi\left(X_{T}\right)+\int_{s}^{\xi_{s} \wedge T} f_{u}\left(t, X_{t}\right) d t\right. \\
\\
\left.+\int_{s}^{\xi_{s} \wedge T} d A_{s, t}^{\mu}\right\}
\end{gathered}
$$

for q.e. $(s, x) \in D_{T}$.

## Remark

$u$ is an entropy solution of $(* *)$.

## Renormalized solutions

## Theorem (Droniou, Porretta \& Prignet)

Each measure $\mu \in \mathcal{M}_{0, b}\left(D_{T}\right)$ admits a decomposition of the form

$$
\mu=g_{t}+\operatorname{div}(G)+f
$$

where $g \in L^{2}\left(0, T ; H_{0}^{1}(D)\right), G=\left(G^{1}, \ldots, G^{d}\right) \in L^{2}\left(D_{T}\right)^{d}$, $f \in L^{1}\left(D_{T}\right)$.

Remark. The above decomposition means that

$$
\int_{D_{T}} \eta d \mu=-\int_{0}^{T}\left\langle g, \frac{\partial \eta}{\partial t}\right\rangle d t-(G, \nabla \eta)_{L^{2}}+\int_{D_{T}} f \eta d m_{1}
$$

for every $\eta \in \mathcal{W}\left(D_{T}\right)$ ( $m_{1}$ denotes the Lebesgue measure on $D_{T}$ ), where

$$
\mathcal{W}=\left\{\eta \in L^{2}\left(0, T ; H_{0}^{1}(D)\right): \frac{\partial \eta}{\partial t} \in L^{2}\left(0, T ; H^{-1}(D)\right)\right.
$$

## Renormalized solutions

## Definition (Droniou, Porretta \& Prignet)

A measurable $u: D_{T} \rightarrow \mathbb{R}$ is a renormalized solution of $(* *)$ if
(a) $f_{u} \in L^{1}\left(D_{T}\right)$,
(b) For some decomposition $(g, G, f)$ of $\mu$,

$$
\begin{gathered}
u-g \in L^{\infty}\left(0, T ; L^{2}(D)\right), T_{k}(u-g) \in L^{2}\left(0, T ; H^{1}(D)\right) \text { and } \\
\lim _{n \rightarrow+\infty} \int_{\{n \leq|u-g| \leq n+1\}}|\nabla u| d m_{1}=0,
\end{gathered}
$$

(c) For any $S \in W^{2, \infty}(\mathbb{R})$ with compact support,

$$
\begin{aligned}
& \frac{\partial}{\partial t}(S(u-g))+\operatorname{div}\left(a \nabla u S^{\prime}(u-g)\right)-S^{\prime \prime}(u-g) a \nabla u \cdot \nabla(u-g) \\
& \quad=-S^{\prime}(u-g) f-\operatorname{div}\left(G S^{\prime}(u-g)\right)+G S^{\prime \prime}(u-g) \cdot \nabla(u-g)
\end{aligned}
$$

in the sense of distributions,
(d) $T_{k}(u-g)(T)=T_{k}(\varphi)$ in $L^{2}(D)$ for all $k \geq 0$.

## Parabolic obstacle problem

## Definition

We say that a pair $(u, \nu)$ consisting of a measurable function $u: D_{T} \rightarrow \mathbb{R}$ and a measure $\nu$ on $D_{T}$ is a solution of $(*)$ if
(a) $f_{u} \in L^{1}\left(D_{T}\right), \nu \in \mathcal{M}_{0, b}\left(D_{T}\right), h_{1} \leq u \leq h_{2}$, $m_{1}$-a.e.,
(b) For q.e. $(s, x) \in D_{T}$,

$$
\begin{gathered}
u(s, x)=E_{s, x}\left\{1_{\left\{\xi_{s}>T\right\}} \varphi\left(X_{T}\right)+\int_{s}^{\xi_{s} \wedge T} f_{u}\left(t, X_{t}\right) d t\right. \\
\left.+\int_{s}^{\xi_{s} \wedge T} d\left(A_{s, t}^{\mu}+A_{s, t}^{\nu}\right)\right\}
\end{gathered}
$$

i.e. $u$ is a renormalized solution of the problem

$$
\left\{\begin{array}{l}
\frac{\partial u}{\partial t}+A u=-f_{u}-\mu-\nu \text { on }(0, T) \times D \\
u(T, \cdot)=\varphi, \quad u(t, \cdot)_{\mid \partial D}=0, \quad t \in(0, T) .
\end{array}\right.
$$

## Parabolic obstacle problem

We say that $u \in \mathcal{F D}$ if the process $[s, T] \mapsto u\left(t, X_{t}\right)$ is càdlàg under $P_{s, x}$ for q.e. $(s, x) \in D_{T}$.

## Definition (continued)

(c) For every $h_{1}^{*}, h_{2}^{*} \in \mathcal{F D}$ such that $h_{1} \leq h_{1}^{*} \leq u \leq h_{2}^{*} \leq h_{2}$, $m_{1}$-a.e. we have

$$
\int_{s}^{\xi_{s} \wedge T}\left(u\left(t, X_{t}\right)-h_{1-}^{*}\left(t, X_{t}\right)\right) d A_{s, t}^{\nu^{+}}=0, \quad P_{s, x^{-}} \text {a.s. }
$$

and

$$
\begin{gathered}
\qquad \int_{s}^{\xi_{s} \wedge T}\left(h_{2-}^{*}\left(t, X_{t}\right)-u\left(t, X_{t}\right)\right) d A_{s, t}^{\nu^{-}}=0, \quad P_{s, x^{-}-\mathrm{a} . \mathrm{s}} \\
\text { for q.e. }(s, x) \in D_{T}\left(\text { Here } h_{i-}^{*}\left(t, X_{t}\right)=\lim _{s<t, s \rightarrow t} h_{i}^{*}\left(s, X_{s}\right)\right)
\end{gathered}
$$

Comments.
(1) If $h_{1}, h_{2}$ are quasi-continuous and $h_{1}(T, \cdot) \leq \varphi \leq h_{2}(T, \cdot)$, $m$-a.e. then condition (c) says that

$$
\int_{D_{T}}\left(u-h_{1}\right) d \nu^{+}=\int_{D_{T}}\left(h_{2}-u\right) d \nu^{-}=0 .
$$

(2) In the linear case with $L^{2}$ data condition (c) coincides with the condition introduced by M. Pierre (1979).

Additional assumption.
(H4) There exists a renormalized solution $v$ of the problem

$$
\left\{\begin{array}{l}
\frac{\partial v}{\partial t}+A v=-\lambda, \\
v(T, \cdot)=\psi, \quad v(t, \cdot)_{\mid \partial D}=0, \quad t \in(0, T)
\end{array}\right.
$$

with some $\lambda \in \mathcal{M}_{0, b}\left(D_{T}\right)$ and measurable $\psi$ satisfying $\psi \geq \varphi$ such that $f_{v} \in L^{1}\left(D_{T}\right)$ and $h_{1} \leq v \leq h_{2}, m_{1}$-a.e. on $D_{T}$.

## Parabolic obstacle problem - main result

## Theorem (T. Klimsiak, A.R.)

Assume (H1)-(H4).
(i) There exists a unique solution $(u, \nu)$ of $(*)$. Moreover, (a) $u \in \mathcal{F D}$ and

$$
E_{s, x} \sup _{s \leq t \leq T}\left|u\left(t, X_{t}\right)\right|^{q}<\infty, \quad E_{s, x}\left(\int_{s}^{T}\left|u\left(t, X_{t}\right)\right|^{2} d t\right)^{q / 2}<\infty
$$

$$
\text { for } q \in(0,1) \text {, }
$$

(b) $T_{k} u \in L^{2}\left(0, T ; H_{0}^{1}(D)\right)$ for $k>0$, where $T_{k} u=(-k) \vee u \wedge k$, (c) $u \in L^{q}\left(0, T ; W_{0}^{1, q}(D)\right)$ for $q<\frac{d+2}{d+1}$.
(ii) If $h_{1}, h_{2}$ are quasi-continuous and $h_{1}(T, \cdot) \leq \varphi \leq h_{2}(T, \cdot)$, $m$-a.e. then $u$ is quasi-continuous.

## Parabolic obstacle problem - main result

## Theorem (continued)

(iii) Let $u_{n}$ be a renormalized solution of the problem

$$
\left\{\begin{array}{l}
\frac{\partial u_{n}}{\partial t}+A_{t} u_{n}=-f_{u_{n}}-\mu-n\left(u_{n}-h_{1}\right)^{-}+n\left(u_{n}-h_{2}\right)^{-} \\
u_{n}(T, \cdot)=\varphi, \quad u_{n}(t, \cdot)_{\mid \partial D}=0, \quad t \in(0, T)
\end{array}\right.
$$

Then $u_{n} \rightarrow u$ q.e. on $D_{T}$ and $\nabla u_{n} \rightarrow \nabla u$ in measure $m_{1}$,
(iv) If $h_{2}=+\infty$ then $\nu_{n} \rightarrow \nu$ weakly, where $\nu_{n}=n\left(u_{n}-h_{1}\right)^{-}$.

Similar statement in case $h_{1}=-\infty$. In the general case more complicated formulation.

## Sketch of proof (for $\varphi=0$ )

(i) We prove existence of a unique solution $(Y, Z, L)$ of RBSDE

$$
\begin{aligned}
Y_{t}= & \int_{t \wedge t}^{\tau} f\left(X_{t}, Y_{t}\right) d t+\int_{\tau \wedge t}^{\tau} d A_{t}^{\mu} \\
& +\int_{\tau \wedge t}^{\tau} d L_{t} d t+\int_{\tau \wedge t}^{\tau} d M_{s}, \quad P_{s, x} \text {-a.s. }
\end{aligned}
$$

for q.e. $(s, x) \in D_{T}$ and show that $L=A^{\nu}$ for some $\nu \in \mathcal{M}_{0, b}$.
(ii) Taking $t=s$ and integrating with respect to $P_{s, x}$ we conclude that $u$ defined by $u(s, x)=Y_{s}, P_{s, x}$-a.s. satisfies the nonlinear Fenynman-Kac formula

$$
u(s, x)=E_{s, x}\left\{\int_{s}^{\xi_{s} \wedge T} f_{u}\left(t, X_{t}\right) d t+\int_{s}^{\xi_{s} \wedge T} d\left(A_{s, t}^{\mu}+A_{s, t}^{\nu}\right)\right\}
$$

(iii) We show that $f_{u} \in L^{1}\left(D_{T}\right)$.

## Sketch of proof (for $\varphi=0$ )

(iv) We know that

$$
u(s, x)=E_{s, x} \int_{s}^{\xi_{s} \wedge T} d A_{s, t}^{\gamma}, \quad \gamma=f_{u} \cdot m+\mu+\nu
$$

We choose a generalized nest $\left\{F_{n}\right\}$ (i.e. $F_{n} \subset F_{n+1}$,
$\left.\operatorname{cap}\left(K \backslash F_{n}\right) \rightarrow 0,|\gamma|\left(D_{T} \backslash \bigcup_{n=1}^{\infty} F_{n}\right)=0\right)$ such that
$1_{F_{n}} \cdot \gamma \in \mathcal{M}_{0, b} \cap \mathcal{W}^{\prime}$, where $\mathcal{W}^{\prime}$ is the space dual to the space

$$
\mathcal{W}=\left\{\eta \in L^{2}\left(0, T ; H_{0}^{1}(D)\right): \frac{\partial \eta}{\partial t} \in L^{2}\left(0, T ; H^{-1}(D)\right)\right.
$$

and we define

$$
u_{n}(s, x)=E_{s, x} \int_{s}^{\xi_{s} \wedge T} A_{s, t}^{1_{F_{n}} \cdot \gamma} .
$$

## Sketch of proof (for $\varphi=0$ )

(iv) Then ( $L^{2}$ theory of linear equations) $u_{n}$ is a weak solution of the problem

$$
\left\{\begin{array}{l}
\frac{\partial u_{n}}{\partial t}+A u_{n}=-\mathbf{1}_{F_{n}} \cdot \gamma \text { on }(0, T) \times D, \\
u_{n}(T, \cdot)=0, \quad u_{n}(t, \cdot)_{\mid \partial D}=0, \quad t \in(0, T),
\end{array}\right.
$$

and hence $u_{n}$ is a renormalized solution.
(v) Since $\left\|1_{F_{n}} \cdot \gamma-\left(f_{u} \cdot m+\mu+\nu\right)\right\|_{T V}$, it follows that $u_{n} \rightarrow u$ q.e. in $D_{T}$ and $u$ is a renormalized solution of $(* *)$.
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