Brownian couplings and applications

Mihai N. Pascu

Transilvania University of Braşov, Romania

6th International Conference on Stochastic Analysis and Its Applications

Bedlewo, Poland, September 10 - 14, 2012

In this talk, we will present two such couplings: the scaling coupling and the mirror coupling.

As an application of the scaling coupling, we will prove a monotonicity of the lifetime of reflecting Brownian motion with killing, which implies the validity of the Hot Spots conjecture of J. Rauch for a certain class of domains.

As applications of the mirror coupling, we will present the proof of the Laugesen-Morpurgo conjecture, and a unifying proof of the results of I. Chavel and W. Kendall on Chavel's conjecture.

Time-permitting, I will discuss some recent results on translation coupling and its applications.

In this talk, we will present two such couplings: the scaling coupling and the mirror coupling.

As an application of the scaling coupling, we will prove a monotonicity of the lifetime of reflecting Brownian motion with killing, which implies the validity of the Hot Spots conjecture of J. Rauch for a certain class of domains.

As applications of the mirror coupling, we will present the proof of the Laugesen-Morpurgo conjecture, and a unifying proof of the results of I. Chavel and W. Kendall on Chavel's conjecture.

Time-permitting, I will discuss some recent results on translation coupling and its applications.

In this talk, we will present two such couplings: the scaling coupling and the mirror coupling.

As an application of the scaling coupling, we will prove a monotonicity of the lifetime of reflecting Brownian motion with killing, which implies the validity of the Hot Spots conjecture of J. Rauch for a certain class of domains.

As applications of the mirror coupling, we will present the proof of the Laugesen-Morpurgo conjecture, and a unifying proof of the results of I. Chavel and W. Kendall on Chavel's conjecture.

Time-permitting, I will discuss some recent results on translation coupling and its applications.

In this talk, we will present two such couplings: the scaling coupling and the mirror coupling.

As an application of the scaling coupling, we will prove a monotonicity of the lifetime of reflecting Brownian motion with killing, which implies the validity of the Hot Spots conjecture of J. Rauch for a certain class of domains.

As applications of the mirror coupling, we will present the proof of the Laugesen-Morpurgo conjecture, and a unifying proof of the results of I. Chavel and W. Kendall on Chavel's conjecture.

Time-permitting, I will discuss some recent results on translation coupling and its applications.

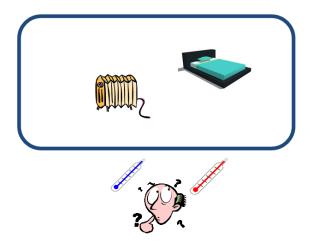
In this talk, we will present two such couplings: the scaling coupling and the mirror coupling.

As an application of the scaling coupling, we will prove a monotonicity of the lifetime of reflecting Brownian motion with killing, which implies the validity of the Hot Spots conjecture of J. Rauch for a certain class of domains.

As applications of the mirror coupling, we will present the proof of the Laugesen-Morpurgo conjecture, and a unifying proof of the results of I. Chavel and W. Kendall on Chavel's conjecture.

Time-permitting, I will discuss some recent results on translation coupling and its applications.

・ロト ・聞 ト ・ ヨト ・ ヨト



- Where should I put the bed, to keep warm in the long run?

Consider u(t, x) the solution of the Neumann heat equation in a smooth bounded domain $D \subset \mathbb{R}^d$ with generic initial condition u_0 . Let x^+ be the hot spot at time *t* and x^- be the cold spot, i.e.

$$u(t, x_t^+) = \max_{x \in \overline{D}} u(t, x)$$
 and $u(t, x_t^-) = \min_{x \in \overline{D}} u(t, x)$

If the second Neumann eigenvalue λ_2 is simple, and φ_2 is a corresponding second Neumann eigenfunction, for large *t* we have

$$u(t,x) = \int_{D} u_0 + e^{-\lambda_2 t} \varphi_2(x) \int_{D} u_0 \varphi_2 + R_2(t,x) \approx c_0 + c_1 e^{-\lambda_2 t} \varphi_2(x) ,$$

so x_t^+ and x_t^- are close to the maximum/minimum points of φ_2 . Hot spots (x_t^+) and cold spots (x_t^-) repel each other, so the distance between them tends to increase wrt *t*. In convex domains, the maximum distance is attained for points on the boundary. Together with the above, this suggests the following.

Consider u(t, x) the solution of the Neumann heat equation in a smooth bounded domain $D \subset \mathbb{R}^d$ with generic initial condition u_0 . Let x_t^+ be the hot spot at time *t* and x_t^- be the cold spot, i.e.

$$u(t, x_t^+) = \max_{x \in \overline{D}} u(t, x)$$
 and $u(t, x_t^-) = \min_{x \in \overline{D}} u(t, x)$

If the second Neumann eigenvalue λ_2 is simple, and φ_2 is a corresponding second Neumann eigenfunction, for large *t* we have

$$u(t,x) = \int_{D} u_0 + e^{-\lambda_2 t} \varphi_2(x) \int_{D} u_0 \varphi_2 + R_2(t,x) \approx c_0 + c_1 e^{-\lambda_2 t} \varphi_2(x) ,$$

so x_t^+ and x_t^- are close to the maximum/minimum points of φ_2 . Hot spots (x_t^+) and cold spots (x_t^-) repel each other, so the distance between them tends to increase wrt *t*. In convex domains, the maximum distance is attained for points on the boundary. Together with the above, this suggests the following.

Consider u(t, x) the solution of the Neumann heat equation in a smooth bounded domain $D \subset \mathbb{R}^d$ with generic initial condition u_0 . Let x_t^+ be the hot spot at time *t* and x_t^- be the cold spot, i.e.

$$u(t, x_t^+) = \max_{x \in \overline{D}} u(t, x)$$
 and $u(t, x_t^-) = \min_{x \in \overline{D}} u(t, x)$

If the second Neumann eigenvalue λ_2 is simple, and φ_2 is a corresponding second Neumann eigenfunction, for large *t* we have

$$u(t,x) = \int_{D} u_0 + e^{-\lambda_2 t} \varphi_2(x) \int_{D} u_0 \varphi_2 + R_2(t,x) \approx c_0 + c_1 e^{-\lambda_2 t} \varphi_2(x),$$

so x_t^+ and x_t^- are close to the maximum/minimum points of φ_2 . Hot spots (x_t^+) and cold spots (x_t^-) repel each other, so the distance between them tends to increase wrt *t*. In convex domains, the maximum distance is attained for points on the boundary. Together with the above, this suggests the following.

Consider u(t, x) the solution of the Neumann heat equation in a smooth bounded domain $D \subset \mathbb{R}^d$ with generic initial condition u_0 . Let x_t^+ be the hot spot at time *t* and x_t^- be the cold spot, i.e.

$$u(t, x_t^+) = \max_{x \in \overline{D}} u(t, x)$$
 and $u(t, x_t^-) = \min_{x \in \overline{D}} u(t, x)$

If the second Neumann eigenvalue λ_2 is simple, and φ_2 is a corresponding second Neumann eigenfunction, for large *t* we have

$$u(t,x) = \int_{D} u_0 + e^{-\lambda_2 t} \varphi_2(x) \int_{D} u_0 \varphi_2 + R_2(t,x) \approx c_0 + c_1 e^{-\lambda_2 t} \varphi_2(x),$$

so x_t^+ and x_t^- are close to the maximum/minimum points of φ_2 . Hot spots (x_t^+) and cold spots (x_t^-) repel each other, so the distance between them tends to increase wrt *t*. In convex domains, the maximum distance is attained for points on the boundary.

Fogether with the above, this suggests the following.

Couplings of RBM 4/31

Consider u(t, x) the solution of the Neumann heat equation in a smooth bounded domain $D \subset \mathbb{R}^d$ with generic initial condition u_0 . Let x_t^+ be the hot spot at time *t* and x_t^- be the cold spot, i.e.

$$u(t, x_t^+) = \max_{x \in \overline{D}} u(t, x)$$
 and $u(t, x_t^-) = \min_{x \in \overline{D}} u(t, x)$

If the second Neumann eigenvalue λ_2 is simple, and φ_2 is a corresponding second Neumann eigenfunction, for large *t* we have

$$u(t,x) = \int_{D} u_0 + e^{-\lambda_2 t} \varphi_2(x) \int_{D} u_0 \varphi_2 + R_2(t,x) \approx c_0 + c_1 e^{-\lambda_2 t} \varphi_2(x),$$

so x_t^+ and x_t^- are close to the maximum/minimum points of φ_2 . Hot spots (x_t^+) and cold spots (x_t^-) repel each other, so the distance between them tends to increase wrt *t*. In convex domains, the maximum distance is attained for points on the boundary.

Together with the above, this suggests the following.

M. N. Pascu (Transilvania Univ)

Couplings of RBM 4/31

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and \u03c6₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

• B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d

- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.
- **HS still open** in its full generality! (e.g., proof for acute triangles?...

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Conjecture 1 (Hot Spots conjecture)

Maxima and minima of second Neumann eigenfunctions of convex bounded domains are attained (only) on the boundary of the domain.

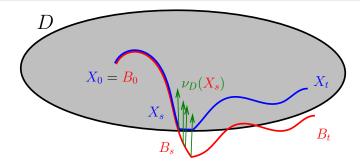
- B. Kawohl: true for balls, annuli, parallelipipeds in \mathbb{R}^d
- K. Burdzy and W. Werner: counterexample (non-convex domain): minimum inside the domain, maximum on the boundary
- R. Bass and K. Burdzy: stronger counterexample (non-convex domain): both minimum and maximum inside the domain
- D. Jerisson and N. Nadirashvili: true if the domain has two orthogonal axis of symmetry
- R. Bañuelos and K. Burdzy: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ symmetric wrt it
- MNP: true if there are two orthogonal axes of symmetry, or just one axis of symmetry and φ₂ antisymmetric wrt it, or ... (some condition on the nodal set of φ₂)
- Other results: true for obtuse triangles, for some some doubly connected domains, for nearly circular domains.

Definition 2 (Reflecting Brownian motion)

Reflecting Brownian motion in $D \subset \mathbb{R}^d$ starting at $x_0 \in \overline{D}$: a solution to

$$X_{t} = x_{0} + B_{t} + \int_{0}^{t} \nu_{D}(X_{s}) dL_{s}^{X}, \qquad t \ge 0,$$
(1)

where B_t is a *d*-dimensional Brownian motion starting at origin, ν_D is the inward unit vector field on ∂D , L_t^X is the local time of X on ∂D .

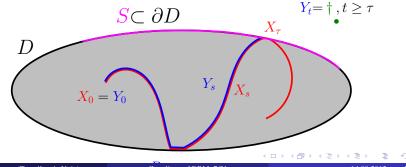


Definition 3 (Reflecting Brownian motion with killing)

Reflecting Brownian motion in *D* killed on hitting $S \subset \partial D$, starting at $x_0 \in \overline{D}$:

$$Y_t = \begin{cases} X_t, & t < \tau \\ \dagger, & t \ge \tau \end{cases},$$
(2)

where X_t is RBM in *D* starting at x_0 , $\tau = \tau_S = \inf\{t > 0 : X_t \in S\}$ is the killing time, and $\dagger \notin D$ is the cemetery state.



M. N. Pascu (Transilvania Univ)

Couplings of RBM 7/31

- Synchronous coupling: $(B_t, B_t + v)$
- Mirror coupling: (B_t, RB_t)
- Scaling coupling: $(B_t, cB_{t/c^2})$

- Synchronous coupling: $(B_t, B_t + v)$
- Mirror coupling: (B_t, RB_t)
- Scaling coupling: $(B_t, cB_{t/c^2})$

- Synchronous coupling: $(B_t, B_t + v)$
- Mirror coupling: (B_t, RB_t)
- Scaling coupling: $(B_t, cB_{t/c^2})$

- Synchronous coupling: $(B_t, B_t + v)$
- Mirror coupling: (B_t, RB_t)
- Scaling coupling: $(B_t, cB_{t/c^2})$

This gives rise to:

- Synchronous coupling: $(B_t, B_t + v)$
- Mirror coupling: (B_t, RB_t)
- Scaling coupling: $(B_t, cB_{t/c^2})$

The above can be extended to the case of reflecting Brownian motion.

Couplings of RBM:

• Synchronous coupling: (R. Atar, K. Burdzy, R. Bañuelos, Z. Q. Chen, M. Cranston)

Couplings of RBM:

- Synchronous coupling: (R. Atar, K. Burdzy, R. Bañuelos, Z. Q. Chen, M. Cranston)
- Mirror coupling : (W. S. Kendal, M. Cranston, R. Atar, K. Burdzy, R. Bañuelos, MNP)

Couplings of RBM:

- Synchronous coupling: (R. Atar, K. Burdzy, R. Bañuelos, Z. Q. Chen, M. Cranston)
- Mirror coupling : (W. S. Kendal, M. Cranston, R. Atar, K. Burdzy, R. Bañuelos, MNP)
- Scaling coupling : (MNP)

Lemma 4 ("Multiplicative Skorokhod lemma" in the unit disk, MNP)

If B_t is a 2-dimensional BM, $M_t = 1 \vee \sup_{s \le t} |B_s|$ and $\alpha_t^{-1} = A_t = \int_0^t \frac{1}{M_s^2} ds$,

$$X_t = rac{1}{M_{lpha_t}} B_{lpha_t}, \qquad t \geq 0$$

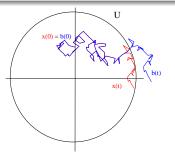
is a RBM in $U = \{z \in \mathbb{R}^2 : |z| < 1\}.$

Lemma 4 ("Multiplicative Skorokhod lemma" in the unit disk, MNP)

If B_t is a 2-dimensional BM, $M_t = 1 \vee \sup_{s \le t} |B_s|$ and $\alpha_t^{-1} = A_t = \int_0^t \frac{1}{M_s^2} ds$,

$$X_t = rac{1}{M_{lpha_t}} B_{lpha_t}, \qquad t \ge 0$$

is a RBM in $U = \{z \in \mathbb{R}^2 : |z| < 1\}.$

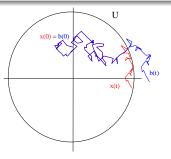


Lemma 4 ("Multiplicative Skorokhod lemma" in the unit disk, MNP)

If B_t is a 2-dimensional BM, $M_t = 1 \vee \sup_{s \le t} |B_s|$ and $\alpha_t^{-1} = A_t = \int_0^t \frac{1}{M_s^2} ds$,

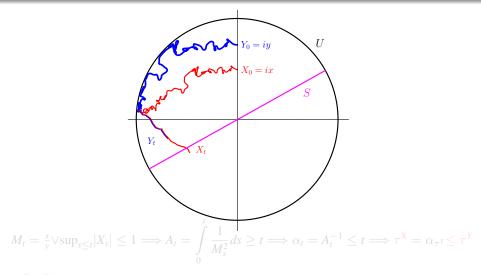
$$X_t = rac{1}{M_{lpha_t}} B_{lpha_t}, \qquad t \ge 0$$

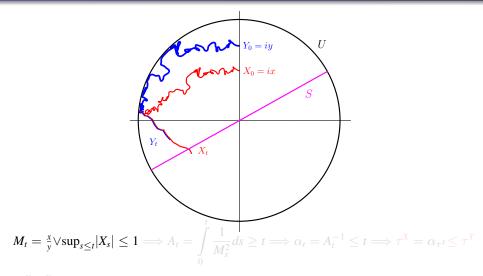
is a RBM in $U = \{z \in \mathbb{R}^2 : |z| < 1\}.$

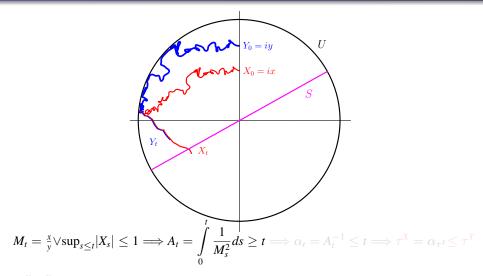


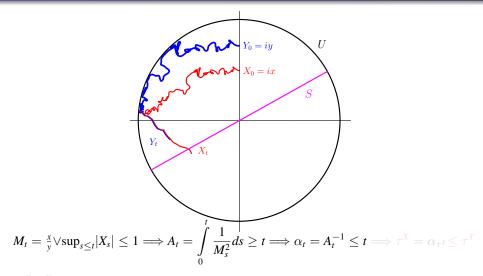
Proof: Itô formula with $f(x, y) = \frac{x}{y}$, B_t and M_t (and a time change).

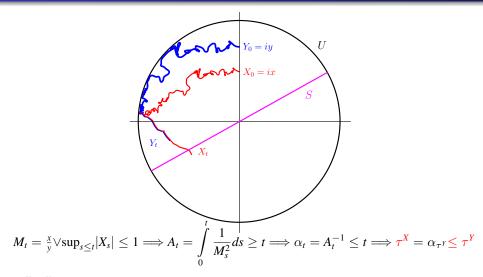
Scaling coupling of RBM in U starting at $(xe^{i\theta}, ye^{i\theta})$ $(0 < x \le y \le 1)$: a pair (X_t, Y_t) , where X_t RBM in U starting at $xe^{i\theta}$, $Y_t = \frac{1}{M_{\alpha}} X_{\alpha_t}$, $M_t = \frac{x}{y} \vee \sup_{s \le t} |X_s|, \text{ and } \alpha_t^{-1} = A_t = \int_0^t \frac{1}{M_z^2} ds.$ U Maran. Y_t X_{t} M. N. Pascu (Transilvania Univ) Couplings of RBM 10/31 14.09.2012 10/31

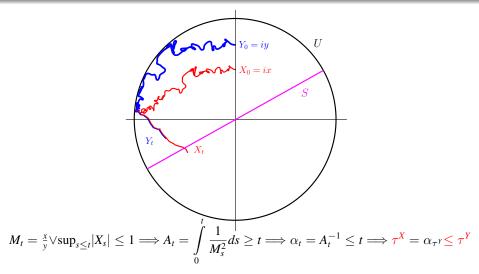












Corollary 5 (Monotonicity of lifetime in the disk)

For any t > 0, $P(\tau^x > t)$ is a radially increasing function in U $(\tau^x \text{ is the lifetime of RBM in U starting at } x, killed on a diameter).$

Remark: for *t* large, $P(\tau^x > t) \approx c e^{-\mu_1 t} \psi_1(x) = c e^{-\lambda_2 t} \varphi_2(x)$.

Theorem 6 (Monotonicity of antisymmetric second Neumann eigenfunctions)

If φ is a second Neumann eigenfunction of the Laplacian on U, antisymmetric with respect to a diameter, then φ is a radially monotone function.

Remark: any second Neumann eigenfunction is antisymmetric in the disk!

Corollary 7 (Hot Spots for the unit disk)

The Hot Spots conjecture holds for the unit disk U, that is for any second Neumann eigenfunction φ of the laplacian on U we have

Corollary 5 (Monotonicity of lifetime in the disk)

For any t > 0, $P(\tau^x > t)$ is a radially increasing function in U $(\tau^x \text{ is the lifetime of RBM in U starting at } x, killed on a diameter).$

Remark: for *t* large, $P(\tau^x > t) \approx c e^{-\mu_1 t} \psi_1(x) = c e^{-\lambda_2 t} \varphi_2(x)$.

If φ is a second Neumann eigenfunction of the Laplacian on U, antisymmetric with respect to a diameter, then φ is a radially monotone function.

Remark: any second Neumann eigenfunction is antisymmetric in the disk!

Corollary 7 (Hot Spots for the unit disk)

The Hot Spots conjecture holds for the unit disk U, that is for any second Neumann eigenfunction φ of the laplacian on U we have

Corollary 5 (Monotonicity of lifetime in the disk)

For any t > 0, $P(\tau^x > t)$ is a radially increasing function in U $(\tau^x \text{ is the lifetime of RBM in U starting at } x, killed on a diameter).$

Remark: for *t* large, $P(\tau^x > t) \approx c e^{-\mu_1 t} \psi_1(x) = c e^{-\lambda_2 t} \varphi_2(x)$.

Theorem 6 (Monotonicity of antisymmetric second Neumann eigenfunctions)

If φ is a second Neumann eigenfunction of the Laplacian on U, antisymmetric with respect to a diameter, then φ is a radially monotone function.

Remark: any second Neumann eigenfunction is antisymmetric in the disk!

Corollary 7 (Hot Spots for the unit disk)

The Hot Spots conjecture holds for the unit disk U, that is for any second Neumann eigenfunction φ of the laplacian on U we have

Corollary 5 (Monotonicity of lifetime in the disk)

For any t > 0, $P(\tau^x > t)$ is a radially increasing function in U $(\tau^x \text{ is the lifetime of RBM in U starting at } x, killed on a diameter).$

Remark: for *t* large, $P(\tau^x > t) \approx c e^{-\mu_1 t} \psi_1(x) = c e^{-\lambda_2 t} \varphi_2(x)$.

Theorem 6 (Monotonicity of antisymmetric second Neumann eigenfunctions)

If φ is a second Neumann eigenfunction of the Laplacian on U, antisymmetric with respect to a diameter, then φ is a radially monotone function.

Remark: any second Neumann eigenfunction is antisymmetric in the disk!

Corollary 7 (Hot Spots for the unit disk)

The Hot Spots conjecture holds for the unit disk U, that is for any second Neumann eigenfunction φ of the laplacian on U we have

Corollary 5 (Monotonicity of lifetime in the disk)

For any t > 0, $P(\tau^x > t)$ is a radially increasing function in $U(\tau^x)$ is the lifetime of RBM in U starting at x, killed on a diameter).

Remark: for *t* large, $P(\tau^x > t) \approx c e^{-\mu_1 t} \psi_1(x) = c e^{-\lambda_2 t} \varphi_2(x)$.

Theorem 6 (Monotonicity of antisymmetric second Neumann eigenfunctions)

If φ is a second Neumann eigenfunction of the Laplacian on U, antisymmetric with respect to a diameter, then φ is a radially monotone function.

Remark: any second Neumann eigenfunction is antisymmetric in the disk!

Corollary 7 (Hot Spots for the unit disk)

The Hot Spots conjecture holds for the unit disk U, that is for any second Neumann eigenfunction φ of the laplacian on U we have

$$\min_{\partial U} \varphi = \min_{\overline{U}} \varphi < \max_{\overline{U}} \varphi = \max_{\partial U} \varphi,$$

More applications of scaling coupling...

The previous result is known (B. Kawohl, [6])... ~

Conformal invariance of RBM + geometric characterization of a convex maps \Rightarrow the same is true for any smooth bounded convex domain $D \subset \mathbb{R}^2$!

Theorem 8 (MNP)

If $D \subset \mathbb{R}^2$ is a convex $C^{1,\alpha}$ domain ($0 < \alpha < 1$), and at least one of the following hypothesis hold,

- i) *D* is symmetric with respect to both coordinate axes;
- ii) *D* is symmetric with respect to the horizontal axis and the diameter to width ratio d_D/l_D is larger than $\frac{4j_0}{\pi} \approx 3.06$;

then Hot Spots conjecture holds for the domain D.

More applications of scaling coupling...

The previous result is known (B. Kawohl, [6])... $\stackrel{\sim}{\rightarrow}$ Conformal invariance of RBM + geometric characterization of a convex maps \Rightarrow the same is true for any smooth bounded convex domain $D \subset \mathbb{R}^2! \stackrel{\sim}{\smile}$

Theorem 8 (MNP)

If $D \subset \mathbb{R}^2$ is a convex $C^{1,\alpha}$ domain ($0 < \alpha < 1$), and at least one of the following hypothesis hold,

- i) *D* is symmetric with respect to both coordinate axes;
- ii) *D* is symmetric with respect to the horizontal axis and the diameter to width ratio d_D/l_D is larger than $\frac{4j_0}{\pi} \approx 3.06$;

then Hot Spots conjecture holds for the domain D.

More applications of scaling coupling...

The previous result is known (B. Kawohl, [6])... Conformal invariance of RBM + geometric characterization of a convex maps

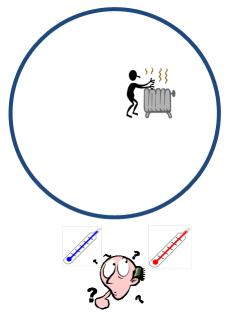
 \Rightarrow the same is true for any smooth bounded convex domain $D \subset \mathbb{R}^2! \stackrel{\sim}{\smile}$

Theorem 8 (MNP)

If $D \subset \mathbb{R}^2$ is a convex $C^{1,\alpha}$ domain ($0 < \alpha < 1$), and at least one of the following hypothesis hold,

- i) D is symmetric with respect to both coordinate axes;
- ii) *D* is symmetric with respect to the horizontal axis and the diameter to width ratio d_D/l_D is larger than $\frac{4j_0}{\pi} \approx 3.06$;

then Hot Spots conjecture holds for the domain D.



- Where should I put the radiator, to feel warmest at all times?

э

Conjecture 9 (R. Laugesen, C. Morpurgo, 1998)

For any t > 0, $p_{\mathbb{U}}(t, x, x)$ is a strictly increasing radial function in the unit ball U, that is

$$p_{\mathbb{U}}(t, x, x) < p_{\mathbb{U}}(t, y, y),$$

for all $x, y \in \overline{\mathbb{U}}$ with ||x|| < ||y||.

Remark: Laugesen-Morpugo conjecture \Rightarrow Hot spots conjecture for the disk.

(3)

Conjecture 9 (R. Laugesen, C. Morpurgo, 1998)

For any t > 0, $p_{U}(t, x, x)$ is a strictly increasing radial function in the unit ball U, that is

$$p_{\mathbb{U}}(t,x,x) < p_{\mathbb{U}}(t,y,y),$$

for all $x, y \in \overline{\mathbb{U}}$ with ||x|| < ||y||.

Remark: Laugesen-Morpugo conjecture \Rightarrow Hot spots conjecture for the disk.

(3)

Was introduced by Kendall ([7]) and Cranston ([Cr]) (BM on manifolds), and developed by Burdzy et al. ([1], [2], [3], ...) (RBM in a smooth domains).

Loosely speaking, in both cases the idea is that the increments of one BM/RBM is the mirror image of the other.

A bit more precise: let X_t , Y_t be RBM is a smooth domain $D \subset R^d$, with driving BM B_t , Z_t , and consider the SDE:

$$Z_{t} = B_{t} - 2 \int_{0}^{t} \frac{X_{s} - Y_{s}}{\left\|X_{s} - Y_{s}\right\|^{2}} \left(X_{s} - Y_{s}\right) \cdot dB_{s}.$$
(4)

Burdzy et al. proved the existence of a strong solution and pathwise uniqueness of the above SDE for $t < \tau = \inf \{s > 0 : X_s = Y_s\}$.

We let $X_t = Y_t$ for $t \ge \tau$, and refer to (X_t, Y_t) as a mirror coupling in D starting at $x, y \in \overline{D}$.

Was introduced by Kendall ([7]) and Cranston ([Cr]) (BM on manifolds), and developed by Burdzy et al. ([1], [2], [3], ...) (RBM in a smooth domains).

Loosely speaking, in both cases the idea is that the increments of one BM/RBM is the mirror image of the other.

A bit more precise: let X_t , Y_t be RBM is a smooth domain $D \subset R^d$, with driving BM B_t , Z_t , and consider the SDE:

$$Z_t = B_t - 2 \int_0^t \frac{X_s - Y_s}{\|X_s - Y_s\|^2} \left(X_s - Y_s\right) \cdot dB_s.$$
(4)

Burdzy et al. proved the existence of a strong solution and pathwise uniqueness of the above SDE for $t < \tau = \inf \{s > 0 : X_s = Y_s\}$.

We let $X_t = Y_t$ for $t \ge \tau$, and refer to (X_t, Y_t) as a mirror coupling in D starting at $x, y \in \overline{D}$.

イロト イヨト イヨト イヨ

Was introduced by Kendall ([7]) and Cranston ([Cr]) (BM on manifolds), and developed by Burdzy et al. ([1], [2], [3], ...) (RBM in a smooth domains).

Loosely speaking, in both cases the idea is that the increments of one BM/RBM is the mirror image of the other.

A bit more precise: let X_t , Y_t be RBM is a smooth domain $D \subset R^d$, with driving BM B_t , Z_t , and consider the SDE:

$$Z_t = B_t - 2 \int_0^t \frac{X_s - Y_s}{\|X_s - Y_s\|^2} (X_s - Y_s) \cdot dB_s.$$
(4)

Burdzy et al. proved the existence of a strong solution and pathwise uniqueness of the above SDE for $t < \tau = \inf \{s > 0 : X_s = Y_s\}$.

We let $X_t = Y_t$ for $t \ge \tau$, and refer to (X_t, Y_t) as a mirror coupling in D starting at $x, y \in \overline{D}$.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Was introduced by Kendall ([7]) and Cranston ([Cr]) (BM on manifolds), and developed by Burdzy et al. ([1], [2], [3], ...) (RBM in a smooth domains).

Loosely speaking, in both cases the idea is that the increments of one BM/RBM is the mirror image of the other.

A bit more precise: let X_t , Y_t be RBM is a smooth domain $D \subset R^d$, with driving BM B_t , Z_t , and consider the SDE:

$$Z_t = B_t - 2 \int_0^t \frac{X_s - Y_s}{\|X_s - Y_s\|^2} (X_s - Y_s) \cdot dB_s.$$
(4)

Burdzy et al. proved the existence of a strong solution and pathwise uniqueness of the above SDE for $t < \tau = \inf \{s > 0 : X_s = Y_s\}$.

We let $X_t = Y_t$ for $t \ge \tau$, and refer to (X_t, Y_t) as a mirror coupling in D starting at $x, y \in \overline{D}$.

・ロト ・ 四ト ・ ヨト ・ ヨト

Was introduced by Kendall ([7]) and Cranston ([Cr]) (BM on manifolds), and developed by Burdzy et al. ([1], [2], [3], ...) (RBM in a smooth domains).

Loosely speaking, in both cases the idea is that the increments of one BM/RBM is the mirror image of the other.

A bit more precise: let X_t , Y_t be RBM is a smooth domain $D \subset R^d$, with driving BM B_t , Z_t , and consider the SDE:

$$Z_t = B_t - 2 \int_0^t \frac{X_s - Y_s}{\|X_s - Y_s\|^2} (X_s - Y_s) \cdot dB_s.$$
(4)

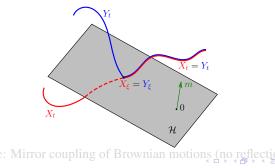
Burdzy et al. proved the existence of a strong solution and pathwise uniqueness of the above SDE for $t < \tau = \inf \{s > 0 : X_s = Y_s\}$.

We let $X_t = Y_t$ for $t \ge \tau$, and refer to (X_t, Y_t) as a mirror coupling in *D* starting at $x, y \in \overline{D}$.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

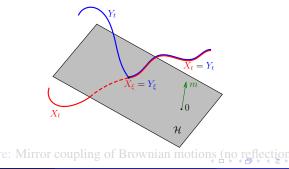
For a unitary vector *m*, let H(m) = I - 2mm' (reflection in the hyperplane through the origin and perpendicular to m), and define $G(x) = H\left(\frac{x}{\|x\|}\right)$ if $x \neq 0$ and G(0) = I.

$$(4) \Longleftrightarrow dZ_t = G\left(\frac{X_t - Y_t}{||X_t - Y_t||}\right) dW_t,$$



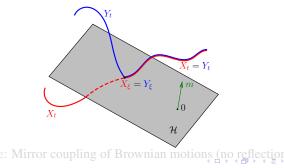
For a unitary vector *m*, let H(m) = I - 2mm' (reflection in the hyperplane through the origin and perpendicular to m), and define $G(x) = H\left(\frac{x}{\|x\|}\right)$ if $x \neq 0$ and G(0) = I.

$$(4) \Longleftrightarrow dZ_t = G\left(\frac{X_t - Y_t}{||X_t - Y_t||}\right) dW_t,$$



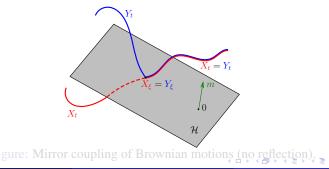
For a unitary vector *m*, let H(m) = I - 2mm' (reflection in the hyperplane through the origin and perpendicular to m), and define $G(x) = H\left(\frac{x}{\|x\|}\right)$ if $x \neq 0$ and G(0) = I.

$$(4) \Longleftrightarrow dZ_t = G\left(\frac{X_t - Y_t}{||X_t - Y_t||}\right) dW_t,$$



For a unitary vector *m*, let H(m) = I - 2mm' (reflection in the hyperplane through the origin and perpendicular to m), and define $G(x) = H\left(\frac{x}{\|x\|}\right)$ if $x \neq 0$ and G(0) = I.

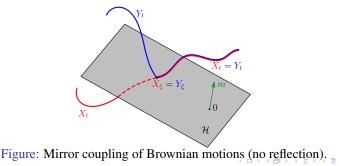
$$(4) \Longleftrightarrow dZ_t = G\left(\frac{X_t - Y_t}{||X_t - Y_t||}\right) dW_t,$$



For a unitary vector *m*, let H(m) = I - 2mm' (reflection in the hyperplane through the origin and perpendicular to m), and define $G(x) = H\left(\frac{x}{\|x\|}\right)$ if $x \neq 0$ and G(0) = I.

$$(4) \Longleftrightarrow dZ_t = G\left(\frac{X_t - Y_t}{||X_t - Y_t||}\right) dW_t,$$

so, (4) says that the increments dZ_t and dB_t are mirror images wrt hyperplane of symmetry \mathcal{M}_t between X_t and Y_t).



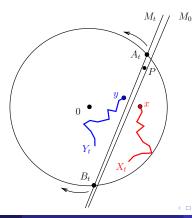
M. N. Pascu (Transilvania Univ)

Couplings of RBM 17/31

14.09.2012 17 / 31

Lemma 10 ("Mirror \mathcal{M}_t moves towards origin", MNP)

Let X_t, Y_t be a mirror coupling of RBM in \mathbb{U} starting at $x, y \in \mathbb{U}$, and let $\tau = \inf\{t > 0 : X_t = Y_t\}$ and $\tau_1 = \inf\{t > 0 : 0 \in \mathcal{M}_t\}$. For all times $t < \tau \land \tau_1$, the mirror \mathcal{M}_t moves towards the origin, in such a way that if a point $P \in \mathbb{U}$ and the origin are separated by \mathcal{M}_{t_1} for $t_1 \in [0, \tau \land \tau_1)$, then the point P and the origin are separated by \mathcal{M}_{t_2} for all $t_2 \in [t_1, \tau \land \tau_1)$.



Inequalities for the Neumann heat kernel $p_{\mathbb{U}}(t, x, y)$ of the unit ball \mathbb{U}

Theorem 11 (MNP)

For any points $x, y, z \in \overline{U}$ such that $||y|| \le ||x||$ and $||x - z|| \le ||y - z||$, and any t > 0 we have:

$$p_{\mathbb{U}}(t, y, z) \le p_{\mathbb{U}}(t, x, z) .$$
(5)

Corollary 12

For any $x \in \mathbb{U} - \{0\}$, $r \in (0, \min\{\|x\|, 1 - \|x\|\})$ and t > 0 we have:

$$\int_{\partial \mathbb{U}} p_{\mathbb{U}}(t, x + ru, x) \, d\sigma(u) \le p_{\mathbb{U}}(t, x + r\frac{x}{\|x\|}, x) \le p_{\mathbb{U}}(t, x + r\frac{x}{\|x\|}, x + r\frac{x}{\|x\|}), \quad (6)$$

where σ is the normalized surface measure on $\partial \mathbb{U}$.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Inequalities for the Neumann heat kernel $p_{\mathbb{U}}(t, x, y)$ of the unit ball \mathbb{U}

Theorem 11 (MNP)

For any points $x, y, z \in \overline{U}$ such that $||y|| \le ||x||$ and $||x - z|| \le ||y - z||$, and any t > 0 we have:

$$p_{\mathbb{U}}(t, y, z) \le p_{\mathbb{U}}(t, x, z).$$
(5)

Corollary 12

For any $x \in \mathbb{U} - \{0\}$, $r \in (0, \min\{\|x\|, 1 - \|x\|\})$ and t > 0 we have:

$$\int_{\partial \mathbb{U}} p_{\mathbb{U}}\left(t, x + ru, x\right) d\sigma(u) \le p_{\mathbb{U}}\left(t, x + r\frac{x}{\|x\|}, x\right) \le p_{\mathbb{U}}\left(t, x + r\frac{x}{\|x\|}, x + r\frac{x}{\|x\|}\right), \quad (6)$$

where σ is the normalized surface measure on $\partial \mathbb{U}$.

イロト (得) (ヨ) (ヨ)

Theorem 13 (MNP)

For any t > 0, $p_{\mathbb{U}}(t, x, x)$ is a strictly increasing radial function in \mathbb{U} , that is

$$p_{\mathbb{U}}(t, x, x) < p_{\mathbb{U}}(t, y, y), \tag{7}$$

Proof.
$$\frac{d}{d\|x\|} p_{\mathbb{U}}(t,x,x) = \lim_{r \searrow 0} \frac{p_{\mathbb{U}}(t,x+r\frac{x}{\|x\|},x+r\frac{x}{\|x\|}) - p_{\mathbb{U}}(t,x,x)}{r}$$

Theorem 13 (MNP)

For any t > 0, $p_{\mathbb{U}}(t, x, x)$ is a strictly increasing radial function in \mathbb{U} , that is

$$p_{\mathbb{U}}(t, x, x) < p_{\mathbb{U}}(t, y, y), \tag{7}$$

Proof.
$$\frac{d}{d\|x\|} p_{\mathbb{U}}(t,x,x) = \lim_{r \searrow 0} \frac{p_{\mathbb{U}}(t,x+r\frac{x}{\|x\|},x+r\frac{x}{\|x\|}) - p_{\mathbb{U}}(t,x,x)}{r}$$

Theorem 13 (MNP)

For any t > 0, $p_{\mathbb{U}}(t, x, x)$ is a strictly increasing radial function in \mathbb{U} , that is

$$p_{\mathbb{U}}(t, x, x) < p_{\mathbb{U}}(t, y, y), \tag{7}$$

Proof.
$$\frac{d}{d\|x\|} p_{\mathbb{U}}(t,x,x) = \lim_{r \searrow 0} \frac{p_{\mathbb{U}}(t,x+r\frac{x}{\|x\|},x+r\frac{x}{\|x\|}) - p_{\mathbb{U}}(t,x,x)}{r}$$
$$\geq \lim_{r \searrow 0} \frac{\int_{\partial \mathbb{U}} p_{\mathbb{U}}(t,x+ru,x) d\sigma(u) - p_{\mathbb{U}}(t,x,x)}{r}$$

Theorem 13 (MNP)

For any t > 0, $p_{\mathbb{U}}(t, x, x)$ is a strictly increasing radial function in \mathbb{U} , that is

$$p_{\mathbb{U}}(t, x, x) < p_{\mathbb{U}}(t, y, y), \tag{7}$$

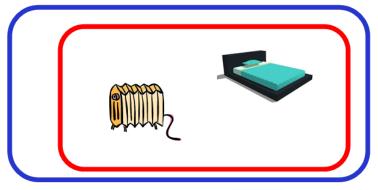
$$\begin{array}{lll} \mathbf{Proof.} & \frac{d}{d\|x\|} p_{\mathbb{U}}\left(t, x, x\right) & = & \lim_{r \searrow 0} \frac{p_{\mathbb{U}}\left(t, x + r\frac{x}{\|x\|}, x + r\frac{x}{\|x\|}\right) - p_{\mathbb{U}}\left(t, x, x\right)}{r} \\ & \geq & \lim_{r \searrow 0} \frac{\int_{\partial \mathbb{U}} p_{\mathbb{U}}\left(t, x + ru, x\right) d\sigma(u) - p_{\mathbb{U}}\left(t, x, x\right)}{r} \\ & = & \int_{\partial \mathbb{U}} \lim_{r \searrow 0} \frac{p_{\mathbb{U}}\left(t, x + ru, x\right) - p_{\mathbb{U}}\left(t, x, x\right)}{r} d\sigma(u) \end{array}$$

Theorem 13 (MNP)

For any t > 0, $p_{\mathbb{U}}(t, x, x)$ is a strictly increasing radial function in \mathbb{U} , that is

$$p_{\mathbb{U}}(t, x, x) < p_{\mathbb{U}}(t, y, y), \tag{7}$$

$$\begin{array}{rcl} \mathbf{Proof.} & \frac{d}{d\|x\|} p_{\mathbb{U}}\left(t, x, x\right) & = & \lim_{r \searrow 0} \frac{p_{\mathbb{U}}\left(t, x + r\frac{x}{\|x\|}, x + r\frac{x}{\|x\|}\right) - p_{\mathbb{U}}\left(t, x, x\right)}{r} \\ & \geq & \lim_{r \searrow 0} \frac{\int_{\partial \mathbb{U}} p_{\mathbb{U}}\left(t, x + ru, x\right) d\sigma(u) - p_{\mathbb{U}}\left(t, x, x\right)}{r} \\ & = & \int_{\partial \mathbb{U}} \lim_{r \searrow 0} \frac{p_{\mathbb{U}}\left(t, x + ru, x\right) - p_{\mathbb{U}}\left(t, x, x\right)}{r} d\sigma(u) \\ & = & \int_{\partial \mathbb{U}} \nabla p_{\mathbb{U}}\left(t, x, x\right) \cdot u \, d\sigma(u) \\ & = & 0. \end{array}$$





- Are we going to be warmer or colder in a bigger apartment??

A D > A A P >
 A

If $D_1 \subset D_2$ are convex domains then for all t > 0 and $x, y \in D_1$ we have

 $p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y)$.

I. Chavel: TRUE, if D_2 is a ball centered at x (or y) and D_1 is convex (integration by parts). W. S. Kendall: TRUE, if D_1 is a ball centered at x (or y) and D_2 is conv

(coupling arguments).

Theorem 15 (Chavel + Kendall)

If $D_1 \subset D_2$ are convex domains then for all t > 0 and $x, y \in D_1$ we have

 $p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y),$

If $D_1 \subset D_2$ are convex domains then for all t > 0 and $x, y \in D_1$ we have

 $p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y)$.

I. Chavel: TRUE, if D_2 is a ball centered at x (or y) and D_1 is convex (integration by parts).

W. S. Kendall: TRUE, if D_1 is a ball centered at x (or y) and D_2 is convex (coupling arguments).

Theorem 15 (Chavel + Kendall)

If $D_1 \subset D_2$ are convex domains then for all t > 0 and $x, y \in D_1$ we have

 $p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y),$

If $D_1 \subset D_2$ are convex domains then for all t > 0 and $x, y \in D_1$ we have

 $p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y)$.

I. Chavel: TRUE, if D_2 is a ball centered at x (or y) and D_1 is convex (integration by parts).

W. S. Kendall: TRUE, if D_1 is a ball centered at x (or y) and D_2 is convex (coupling arguments).

Theorem 15 (Chavel + Kendall)

If $D_1 \subset D_2$ are convex domains then for all t > 0 and $x, y \in D_1$ we have

 $p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y),$

If $D_1 \subset D_2$ are convex domains then for all t > 0 and $x, y \in D_1$ we have

 $p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y)$.

I. Chavel: TRUE, if D_2 is a ball centered at x (or y) and D_1 is convex (integration by parts).

W. S. Kendall: TRUE, if D_1 is a ball centered at x (or y) and D_2 is convex (coupling arguments).

Theorem 15 (Chavel + Kendall)

If $D_1 \subset D_2$ are convex domains then for all t > 0 and $x, y \in D_1$ we have

$$p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y),$$

whenever there exists a ball B centered at either x or y such that $D_1 \subset B \subset D_2$.

Couplings of RBM 22/31

Answer: YES, for example if $D_1 = \mathbb{R}$ and $D_2 = (0, \infty)$: Construction (Tanaka formula): X_t BM in \mathbb{R} , $Y_t = |X_t|$ RBM on $(0, \infty)$ and

$$dY_t = \operatorname{sgn}(X_t) dX_t + dL_t^X, \qquad t \ge 0.$$
(8)

- $D_1 = \mathbb{R}^2$ and D_2 half plane
- $D_1 = \mathbb{R}^2$ and D_2 convex polygonal domain
- $D_1 = \mathbb{R}^2$ and D_2 convex domain
- D_2 convex and $D_2 \subset \subset D_1$

Extension of the mirror coupling

Question: can one define a mirror coupling of Brownian motions living in *different domains* D_1 and D_2 ? **Answer:** YES, for example if $D_1 = \mathbb{R}$ and $D_2 = (0, \infty)$:

Construction (Tanaka formula): X_t BM in \mathbb{R} , $Y_t = |X_t|$ RBM on $(0, \infty)$ and

$$dY_t = \operatorname{sgn}(X_t) dX_t + dL_t^X, \qquad t \ge 0.$$
(8)

- $D_1 = \mathbb{R}^2$ and D_2 half plane
- $D_1 = \mathbb{R}^2$ and D_2 convex polygonal domain
- $D_1 = \mathbb{R}^2$ and D_2 convex domain
- D_2 convex and $D_2 \subset \subset D_1$

Answer: YES, for example if $D_1 = \mathbb{R}$ and $D_2 = (0, \infty)$:

Construction (Tanaka formula): X_t BM in \mathbb{R} , $Y_t = |X_t|$ RBM on $(0, \infty)$ and

$$dY_t = \operatorname{sgn}(X_t) dX_t + dL_t^X, \qquad t \ge 0.$$
(8)

- $D_1 = \mathbb{R}^2$ and D_2 half plane
- $D_1 = \mathbb{R}^2$ and D_2 convex polygonal domain
- $D_1 = \mathbb{R}^2$ and D_2 convex domain
- D_2 convex and $D_2 \subset \subset D_1$

Answer: YES, for example if $D_1 = \mathbb{R}$ and $D_2 = (0, \infty)$:

Construction (Tanaka formula): X_t BM in \mathbb{R} , $Y_t = |X_t|$ RBM on $(0, \infty)$ and

$$dY_t = \operatorname{sgn}(X_t) dX_t + dL_t^X, \qquad t \ge 0.$$
(8)

- $D_1 = \mathbb{R}^2$ and D_2 half plane
- $D_1 = \mathbb{R}^2$ and D_2 convex polygonal domain
- $D_1 = \mathbb{R}^2$ and D_2 convex domain
- D_2 convex and $D_2 \subset \subset D_1$

Answer: YES, for example if $D_1 = \mathbb{R}$ and $D_2 = (0, \infty)$:

Construction (Tanaka formula): X_t BM in \mathbb{R} , $Y_t = |X_t|$ RBM on $(0, \infty)$ and

$$dY_t = \operatorname{sgn}(X_t) dX_t + dL_t^X, \qquad t \ge 0.$$
(8)

- $D_1 = \mathbb{R}^2$ and D_2 half plane
- $D_1 = \mathbb{R}^2$ and D_2 convex polygonal domain
- $D_1 = \mathbb{R}^2$ and D_2 convex domain
- D_2 convex and $D_2 \subset \subset D_1$

Answer: YES, for example if $D_1 = \mathbb{R}$ and $D_2 = (0, \infty)$:

Construction (Tanaka formula): X_t BM in \mathbb{R} , $Y_t = |X_t|$ RBM on $(0, \infty)$ and

$$dY_t = \operatorname{sgn}(X_t) dX_t + dL_t^X, \qquad t \ge 0.$$
(8)

YES, if:

- $D_1 = \mathbb{R}^2$ and D_2 half plane
- $D_1 = \mathbb{R}^2$ and D_2 convex polygonal domain
- $D_1 = \mathbb{R}^2$ and D_2 convex domain

• D_2 convex and $D_2 \subset \subset D_1$

Answer: YES, for example if $D_1 = \mathbb{R}$ and $D_2 = (0, \infty)$:

Construction (Tanaka formula): X_t BM in \mathbb{R} , $Y_t = |X_t|$ RBM on $(0, \infty)$ and

$$dY_t = \operatorname{sgn}(X_t) dX_t + dL_t^X, \qquad t \ge 0.$$
(8)

- $D_1 = \mathbb{R}^2$ and D_2 half plane
- $D_1 = \mathbb{R}^2$ and D_2 convex polygonal domain
- $D_1 = \mathbb{R}^2$ and D_2 convex domain
- D_2 convex and $D_2 \subset \subset D_1$

Extension of the mirror coupling

Question: can one define a mirror coupling of Brownian motions living in *different domains* D_1 and D_2 ? **Answer:** YES, if $D_{1,2} \subset \mathbb{R}^d$ smooth, with non-tangential boundaries, and $D_1 \cap D_2$ convex

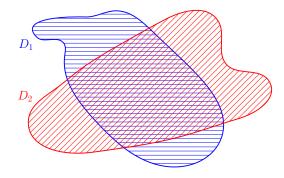


Figure: Typical domains for the extended mirror coupling.

An application of mirror coupling: a unifying proof of Chavel's conjecture

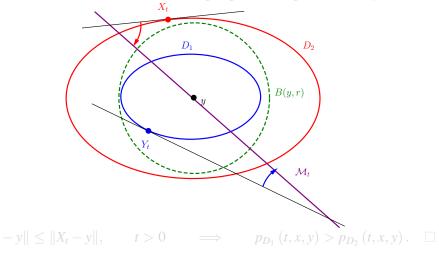
Theorem 16

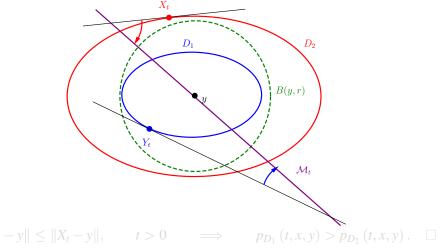
If $D_1 \subset D_2 \subset \mathbb{R}^d$ are smooth and D_1 is a convex domain, then for all t > 0and $x, y \in D_1$ we have

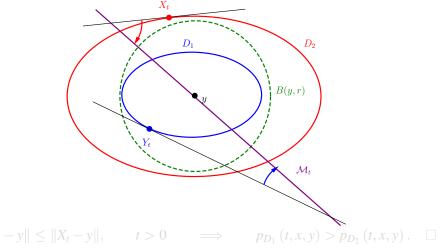
$$p_{D_1}(t, x, y) \ge p_{D_2}(t, x, y),$$

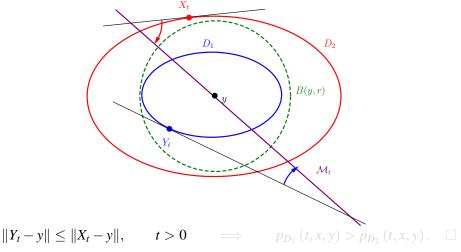
Consider a mirror coupling of RBM X_t , Y_t in D_2 , D_1 , starting at $X_0 = Y_0 = x$.

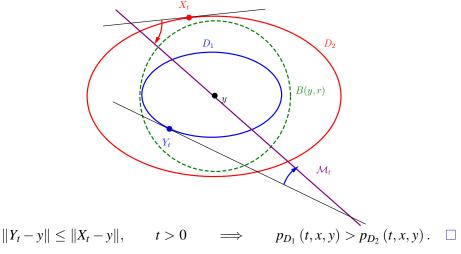
For all t > 0, the mirror \mathcal{M}_t of the coupling cannot separate Y_t and y.



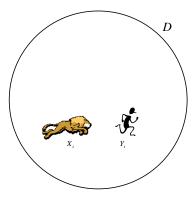








Lion and Man problem (R. Rado, 1953)



Given $x, y \in D$, does there exist X, Y with $X_0 = x, Y_0 = y, |X'_t| = |Y'_t| = 1$ and

$$dist(X_t, Y_t) > c$$
, for all $t > 0$?

(Littlewood, Besicovitch, Croft, Bollobas et. al., Nahin, ...)

M. N. Pascu (Transilvania Univ)

Couplings of RBM 26/31

ε -shy coupling: $P(dist(X_t, Y_t) > \varepsilon \text{ for all } t \ge 0) > 0.$

- bounded convex planar domains with C^2 boundary, without line segments (BBC, 2007).
- bounded convex domains in \mathbb{R}^d , without line segments in the boundary if $d \ge 3$ (Kendall, 2009).
- bounded CAT(0) spaces with boundary satisfying uniform exterior sphere and interior cone conditions, e.g. simply connected bounded planar domains with C^2 boundary (Bramson, Burdzy & Kendall, preprint).

 ε -shy coupling: $P(dist(X_t, Y_t) > \varepsilon \text{ for all } t \ge 0) > 0.$

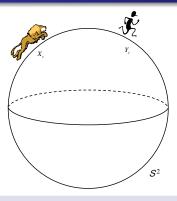
- bounded convex planar domains with C^2 boundary, without line segments (BBC, 2007).
- bounded convex domains in \mathbb{R}^d , without line segments in the boundary if $d \ge 3$ (Kendall, 2009).
- bounded CAT(0) spaces with boundary satisfying uniform exterior sphere and interior cone conditions, e.g. simply connected bounded planar domains with C^2 boundary (Bramson, Burdzy & Kendall, preprint).

 ε -shy coupling: $P(dist(X_t, Y_t) > \varepsilon \text{ for all } t \ge 0) > 0.$

- bounded convex planar domains with C^2 boundary, without line segments (BBC, 2007).
- bounded convex domains in \mathbb{R}^d , without line segments in the boundary if $d \ge 3$ (Kendall, 2009).
- bounded CAT(0) spaces with boundary satisfying uniform exterior sphere and interior cone conditions, e.g. simply connected bounded planar domains with C^2 boundary (Bramson, Burdzy & Kendall, preprint).

 ε -shy coupling: $P(dist(X_t, Y_t) > \varepsilon \text{ for all } t \ge 0) > 0.$

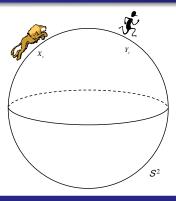
- bounded convex planar domains with C^2 boundary, without line segments (BBC, 2007).
- bounded convex domains in \mathbb{R}^d , without line segments in the boundary if $d \ge 3$ (Kendall, 2009).
- bounded CAT(0) spaces with boundary satisfying uniform exterior sphere and interior cone conditions, e.g. simply connected bounded planar domains with C^2 boundary (Bramson, Burdzy & Kendall, preprint).



Theorem 17

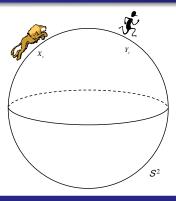
For any $X_0, Y_0 \in S^2$, there exist couplings of BM on S^2 s.t. for all $t \ge 0$ we have

a)
$$|X_t - Y_t| = \sqrt{4 - |y + x|^2 e^{-t}} \nearrow 2$$
 (distance-increasing coupling)
b) $|X_t - Y_t| = |y - x| e^{-t/2} \searrow 0$ (distance-decreasing coupling)
c) $|X_t - Y_t| = |y - x| = const$ (fixed-distance coupling= "translation coupling").



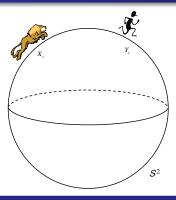
Theorem 17

For any $X_0, Y_0 \in S^2$, there exist couplings of BM on S^2 s.t. for all $t \ge 0$ we have a) $|X_t - Y_t| = \sqrt{4 - |y + x|^2 e^{-t}} \nearrow 2$ (distance-increasing coupling) b) $|X_t - Y_t| = |y - x| e^{-t/2} \searrow 0$ (distance-decreasing coupling) c) $|X_t - Y_t| = |y - x| = const$ (fixed-distance coupling= "translation coupling").



Theorem 17

For any $X_0, Y_0 \in S^2$, there exist couplings of BM on S^2 s.t. for all $t \ge 0$ we have a) $|X_t - Y_t| = \sqrt{4 - |y + x|^2 e^{-t}} \nearrow 2$ (distance-increasing coupling) b) $|X_t - Y_t| = |y - x| e^{-t/2} \searrow 0$ (distance-decreasing coupling) c) $|X_t - Y_t| = |y - x| = const$ (fixed-distance coupling= "translation coupling").



Theorem 17

For any $X_0, Y_0 \in S^2$, there exist couplings of BM on S^2 s.t. for all $t \ge 0$ we have a) $|X_t - Y_t| = \sqrt{4 - |y + x|^2 e^{-t}} \nearrow 2$ (distance-increasing coupling) b) $|X_t - Y_t| = |y - x| e^{-t/2} \searrow 0$ (distance-decreasing coupling) c) $|X_t - Y_t| = |y - x| = const$ (fixed-distance coupling= "translation coupling"). Thank you!



Couplings of RBM 29/31

-

(日)

References



- R. Atar, K. Burdzy, On Neumann eigenfunctions in lip domains, J. Amer. Math. Soc. 17 (2004), pp. 243 265.
- R. Atar, K. Burdzy, Mirror couplings and Neumann eigenfunctions, Indiana Univ. Math. J. 57 (2008), No. 3, pp. 1317 1351.
- K. Burdzy, W. S. Kendall, *Efficient Markovian couplings: Examples and counterexamples*, Ann. Appl. Probab. **10** (2000), No. 2, pp. 362 409.



- M. Cranston, Gradient estimates on manifolds using coupling, J. Funct. Anal. 99 (1991), No.1, 110-124.
- W. Doeblin, *Expose de la Theorie des Chaines simples constantes de Markoff aun nombre fini d'Etats*, Rev. Math. de l'Union Interbalkanique **2** (1938), pp. 77 105.
- B. Kawohl, Rearrangements and convexity of level sets in PDE, Lecture Notes in Mathematics, Vol. 1150, Springer-Verlag, 1985.
- W. S. Kendall, Nonnegative Ricci curvature and the Brownian coupling property, Stochastics 19 (1986), No. 1-2, pp. 111 129.
 - W. S. Kendall, Coupled Brownian motions and partial domain monotonicity for the Neumann heat kernel, J. Funct. Anal. 86 (1989), No. 2, pp. 226 – 236.

- M. N. Pascu, *Scaling coupling of reflecting Brownian motions and the hot spots problem*, Trans. Amer. Math. Soc. **354** (2002), No. 11, pp. 4681 4702.
- M. N. Pascu, Monotonicity properties of Neumann heat kernel in the ball, J. Funct. Anal. 260 (2011), No. 2, pp. 490 500.
- M. N. Pascu, *Mirror coupling of reflecting Brownian motion and an application to Chavel's conjecture*, Electron. J. Probab. **16** (2011), No. 18, pp. 504 530.