# Gradient estimates of *q*-harmonic functions of fractional Schrödinger operator

Tadeusz Kulczycki

Institute of Mathematics and Computer Science Wrocław University of Technology  $X_t$  - the symmetric  $\alpha$ -stable process in  $\mathbb{R}^d$ ,  $\alpha \in (0, 2)$ .  $q : \mathbb{R}^d \to \mathbb{R}$  belongs to the Kato class  $\mathcal{J}^{\alpha}$ .

• We say that a Borel function u on  $\mathbb{R}^d$  is *q*-harmonic in an open set  $D \subset \mathbb{R}^d$  iff

$$u(x) = E^{x}\left[\exp\left(\int_{0}^{\tau_{W}}q(X_{s})\,ds
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• If u is q-harmonic in open set  $D \subset \mathbb{R}^d$  then u is a weak solution of

$$\Delta^{\alpha/2}u + qu = 0, \quad \text{on} \quad D. \tag{1}$$

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 $\Delta^{\alpha/2} := -(-\Delta)^{\alpha/2}$  - the fractional Laplacian.  $\Delta^{\alpha/2} + q$  - the fractional Schrödinger operator.  $X_t$  - the symmetric  $\alpha$ -stable process in  $\mathbb{R}^d$ ,  $\alpha \in (0, 2)$ .  $q : \mathbb{R}^d \to \mathbb{R}$  belongs to the Kato class  $\mathcal{J}^{\alpha}$ .

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 $\begin{array}{l} \Delta^{\alpha/2}:=-(-\Delta)^{\alpha/2} \text{ - the fractional Laplacian.} \\ \Delta^{\alpha/2}+q \text{ - the fractional Schrödinger operator.} \end{array}$ 

 If D ⊂ ℝ<sup>d</sup> is an open bounded set and (D, q) is gaugeable then a weak solution of (1) is a q-harmonic function on D after a modification on a set of Lebesgue measure zero.

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#### Theorem 1

Let  $\alpha \in (0,1]$ ,  $d \in \mathbb{N}$  and  $D \subset \mathbb{R}^d$  be an open bounded set. Assume that  $q: D \to \mathbb{R}$  is Hölder continuous with Hölder exponent  $\eta > 1 - \alpha$ . Let u be q-harmonic in D. If u is nonnegative in  $\mathbb{R}^d$  then  $\nabla u(x)$  exists for any  $x \in D$  and we have

$$|
abla u(x)| \leqslant c rac{u(x)}{\delta_D(x) \wedge 1}, \quad x \in D,$$

where  $\delta_D(x) = \text{dist}(x, \partial D)$  and  $c = c(\alpha, d, q)$ .

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The existence of ∇u(x) and similar gradient estimates are well known: for α = 2, M. Cranston, Z. Zhao (1990), for α ∈ (1,2), K. Bogdan, T. K., A. Nowak (2002).

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- The results for  $\alpha \in (1, 2]$  were shown under the assumption that  $q \in \mathcal{J}^{\alpha-1}$ . The case  $\alpha \in (0, 1]$  is different. In the proof of Theorem 1 probabilistic ideas are used (see e.g. B. Böttcher R Schilling L Wang (2011))

One may ask whether it is possible to weaken the assumption in Theorem 1 that q is Hölder continuous with Hölder exponent  $\eta > 1 - \alpha$ . It occurs that the exponent  $\eta = 1 - \alpha$  is critical in the following sense.

#### Proposition 2

For any  $\alpha \in (0, 1]$ ,  $d \in \mathbb{N}$  and any open bounded set  $D \subset \mathbb{R}^d$  there exists  $q : D \to [0, \infty)$  which is  $1 - \alpha$  Hölder continuous, a function  $u : \mathbb{R}^d \to [0, \infty)$  which is *q*-harmonic in *D* and a point  $z \in D$  such that  $\nabla u(z)$  does not exist.

The proof of this proposition is based on the estimates of the Green function of the killed Brownian motion subordinated by the  $\alpha/2$ -stable subordinator, obtained by R. Song (2004).

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When a *q*-harmonic function *u* vanishes continuously near some part of the boundary of *D* and  $D \subset \mathbb{R}^d$  is a bounded Lipschitz domain then the estimates obtained in Theorem 1 are sharp near that part of the boundary.

#### Theorem 3

Let  $\alpha \in (0, 1]$ ,  $d \in \mathbb{N}$ ,  $D \subset \mathbb{R}^d$  be a bounded Lipschitz domain and  $q: D \to \mathbb{R}$  be Hölder continuous with Hölder exponent  $\eta > 1 - \alpha$ . Let  $V \subset \mathbb{R}^d$  be open and let K be a compact subset of V. Then there exist constants  $c = c(D, V, K, \alpha, q)$  and  $\varepsilon = \varepsilon(D, V, K, \alpha, q)$  such that for every function  $u: \mathbb{R}^d \to [0, \infty)$  which is bounded on V, q-harmonic in  $D \cap V$  and vanishes in  $D^c \cap V$  we have

$$c^{-1}rac{u(x)}{\delta_D(x)}\leqslant |
abla u(x)|\leqslant crac{u(x)}{\delta_D(x)}, \quad x\in K\cap D, \quad \delta_D(x)$$

Similar result was obtained for  $\alpha = 2$  by R. Bañuelos, M. Pang (1999) and for  $\alpha \in (1, 2)$  by K. Bogdan, T. K. A. Nowak (2002) Takener Statement Gradient estimates

Let us consider the eigenvalue problem for the fractional Schrödinger operator on D with zero exterior condition

$$egin{array}{rcl} \Delta^{lpha/2} arphi + q arphi &=& -\lambda arphi & ext{ on } D, \ arphi &=& 0 & ext{ on } D^c. \end{array}$$

It is well known that for the above problem there exists a sequence of eigenvalues  $\{\lambda_n\}_{n=1}^{\infty}$  satisfying

$$\lambda_1 < \lambda_2 \leqslant \lambda_3 \leqslant \dots, \qquad \lim_{n \to \infty} \lambda_n = \infty,$$

and a sequence of corresponding eigenfunctions  $\{\varphi_n\}_{n=1}^{\infty}$ , which can be chosen so that they form an orthonormal basis in  $L^2(D)$ . All  $\varphi_n$  are bounded and continuous on D and  $\varphi_1$  is strictly positive on D.

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## Applications

#### Corollary 4

Assume that  $\alpha \in (0,2)$ ,  $D \subset \mathbb{R}^d$  is an open bounded set,  $q \in \mathcal{J}^{\alpha-1}$  when  $\alpha \in (1,2)$ , or q is Hölder continuous on D with Hölder exponent  $\eta > 1 - \alpha$  when  $\alpha \in (0,1]$ . Then  $\nabla \varphi_n(x)$  exist for any  $n \in \mathbb{N}$ ,  $x \in D$  and we have

$$|
abla arphi_1(x)| \leqslant c rac{arphi_1(x)}{\delta_D(x) \wedge 1}, \qquad x \in D,$$
  
 $|
abla arphi_n(x)| \leqslant rac{c_n}{\delta_D(x) \wedge 1}, \qquad x \in D.$ 

Furthermore, if additionally  $D \subset \mathbb{R}^d$  is a bounded Lipschitz domain then there exists  $\varepsilon = \varepsilon(D, q, \alpha)$  such that

$$|
abla arphi_1(x)| \geqslant c rac{arphi_1(x)}{\delta_D(x)}, \qquad x \in D, \quad \delta_D(x) \leqslant arepsilon.$$

#### Corollary 5

Let  $\alpha \in (0,1)$ ,  $d \in \mathbb{N}$  and  $D \subset \mathbb{R}^d$  be an open bounded set. Assume that  $q: D \to \mathbb{R}$  is Hölder continuous with Hölder exponent  $\eta > 1 - \alpha$  and either u is nonnegative on  $\mathbb{R}^d$  or  $\|u\|_{\infty} < \infty$ . If u is a weak solution of

$$\Delta^{\alpha/2}u + qu = 0, \quad \text{on} \quad D. \tag{2}$$

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then (after a modification on a set of Lebesgue measure zero) u is continuous on D and it is a strong solution of (2).



$$B = B(x_0, r),$$
  

$$r = (\delta_D(x_0)/2) \wedge c,$$
  

$$u(x) = E^x u(X_{\tau_B}) + G_B(qu)(x), \quad x \in B$$

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$$|\nabla f(x_0)| \leq c_1 \frac{f(x_0)}{\delta_B(x_0)} \leq c_2 \frac{u(x_0)}{r}$$

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$$G_D f(x) - G_D f(\hat{x}) = \int_{D_+} (G_D(x, y) - G_D(\hat{x}, y))(f(y) - f(\hat{y})) dy.$$

In order to get estimates of  $\frac{\partial}{\partial x_1}G_D f(0)$  it is enough to get estimates of  $G_D(x, y) - G_D(\hat{x}, y)$ .

X<sub>t</sub> = B<sub>ηt</sub>.
 X<sub>t</sub> - the symmetric α-stable process in ℝ<sup>d</sup>, B<sub>t</sub> - the Brownian motion in ℝ<sup>d</sup>, η<sub>t</sub> - α/2-stable subordinator (starting from 0).

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H = ℝ<sup>d</sup><sub>+</sub> = {x = (x<sub>1</sub>, x<sub>2</sub>,..., x<sub>d</sub>) ∈ ℝ<sup>d</sup> : x<sub>1</sub> > 0}. B<sup>H</sup><sub>t</sub> - the Brownian motion in ℝ<sup>d</sup> killed on exiting H. X̃<sub>t</sub> = (B<sup>H</sup>)<sub>ηt</sub>. X<sup>D</sup><sub>t</sub> - the process X<sub>t</sub> killed on exiting D ~ p<sub>D</sub>(t, x, y). X̃<sub>t</sub><sup>D</sup><sub>+</sub> - the process X̃<sub>t</sub> killed on exiting D<sub>+</sub> ~ p̃<sub>D+</sub>(t, x, y).

#### Lemma

$$\widetilde{p}_{D_+}(t,x,y)=p_D(t,x,y)-p_D(t,\hat{x},y),\quad x,y\in D_+.$$

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#### Lemma

$$\widetilde{p}_{D_+}(t,x,y) = p_D(t,x,y) - p_D(t,\hat{x},y), \quad x,y \in D_+.$$

$$\begin{array}{ll} X^D_t &\sim & G_D(x,y) = \int_0^\infty p_D(t,x,y) \, dt. \\ \tilde{X}^{D_+}_t &\sim & \tilde{G}_{D_+}(x,y) = \int_0^\infty \tilde{p}_{D_+}(t,x,y) \, dt. \\ \text{For symmetric domains } D \subset U \text{ we have } \tilde{G}_{D_+}(x,y) \leqslant \tilde{G}_{U_+}(x,y). \text{ In particular we have } \tilde{G}_{D_+}(x,y) \leqslant \tilde{G}_{R^d_+}(x,y). \\ \text{Let } B = B(0,r), \, x, y \in B_+. \text{ We have} \end{array}$$

$$\begin{array}{lll} G_B(x,y) - G_B(\hat{x},y) &=& \tilde{G}_{B_+}(x,y) \leqslant \tilde{G}_{R_+^d}(x,y) \\ &=& G_{\mathbb{R}^d}(x,y) - G_{\mathbb{R}^d}(\hat{x},y) \\ &=& \frac{c_1}{|x-y|^{d-\alpha}} - \frac{c_1}{|\hat{x}-y|^{d-\alpha}} \\ &\leqslant& \frac{c_2|x-y|}{|x-y|^{d-\alpha}|\hat{x}-y|}. \end{array}$$

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Let α ∈ (0, 1), B = B(0, r). Assume that the function f : B → ℝ is Borel and bounded on B and satisfies

 $|f(x)-f(\hat{x})|\leqslant A|x|^{eta}, \qquad x\in B(0,r/2),$ 

for some constants  $A \ge 1$  and  $\beta \ge 0$ .

• Let  $\alpha \in (0, 1)$ , B = B(0, r). Assume that the function  $f : B \to \mathbb{R}$  is Borel and bounded on B and satisfies  $|f(x) - f(\hat{x})| \leq A|x|^{\beta}, \qquad x \in B(0, r/2),$ 

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• If  $\alpha \in (0, 1)$  and  $\beta \in [0, 1 - \alpha)$  then there exists  $c = c(d, \alpha, \beta)$  such that for any  $x \in B$  we have

$$|G_B f(x) - G_B f(\hat{x})| \leq cA |x|^{\beta+lpha} + c \frac{\sup_{y \in B} f(y)}{r} |x|^{\beta+lpha}.$$

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• Recall that  $u(x) = E^{x}u(X_{\tau_{B}}) + G_{B}(qu)(x)$ . Put f(x) = q(x)u(x).

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- Recall that  $u(x) = E^x u(X_{\tau_B}) + G_B(qu)(x)$ . Put f(x) = q(x)u(x).
- This allows to obtain estimates of  $\frac{\partial}{\partial x_1}G_B(\underline{q}u)(\underline{0})$ .